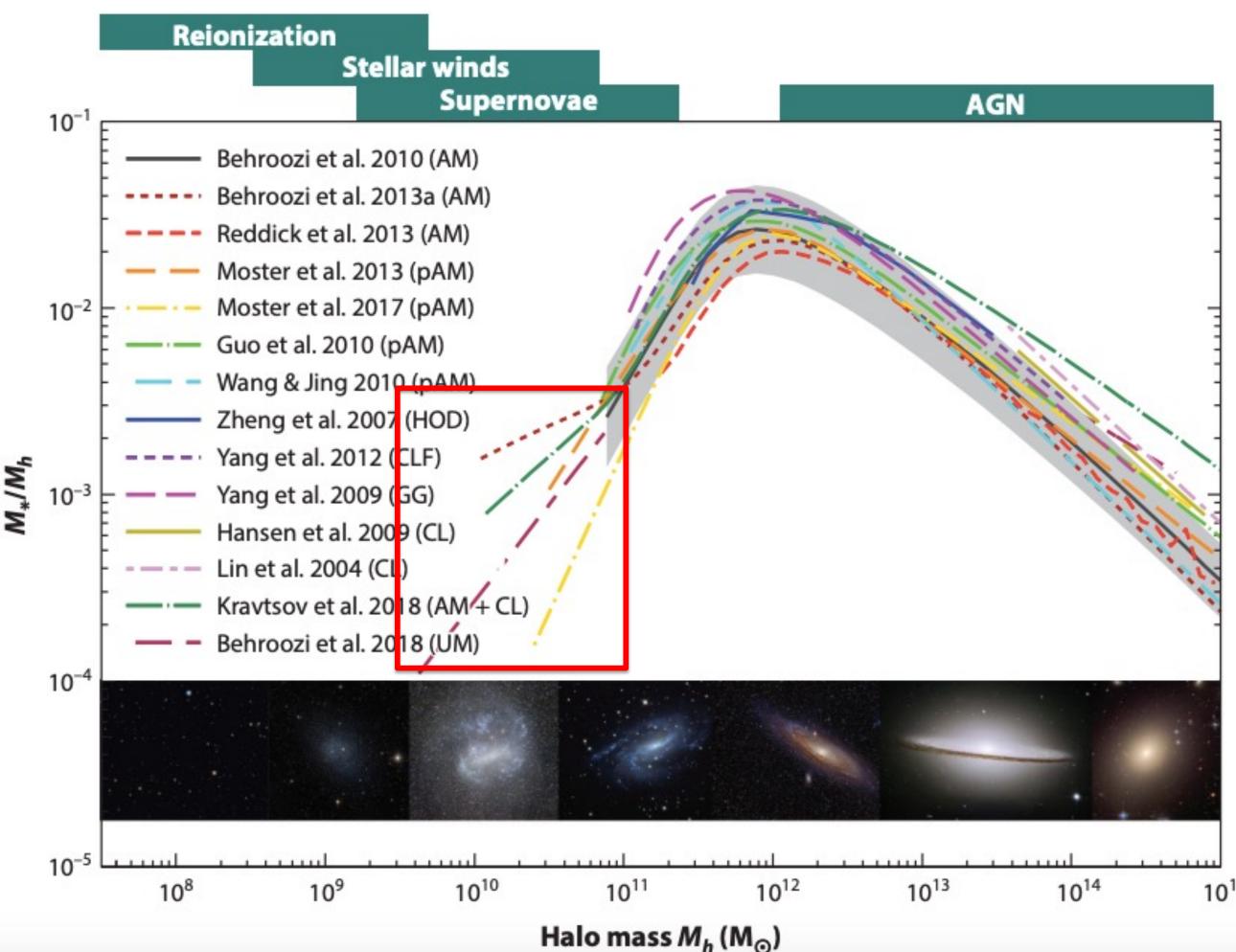
Detecting Low Surface Brightness Galaxies with Mask R-CNN Caleb Levy, Aleksandra Ćiprijanović, Alex Drlica-Wagner, Burçin Mutlu-Pakdil, Brian Nord, Dimitrios Tanoglidis **FERMILAB-POSTER-21-078-STUDENT**

Introduction

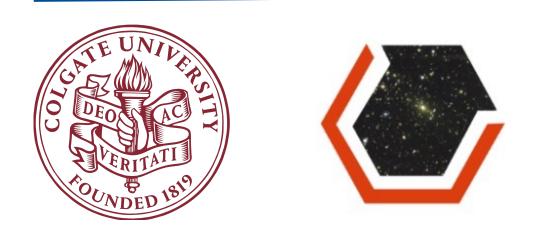
An important aspect of understanding the role of dark matter in our universe is the relationship between galaxies and the dark matter halos hosting them, the galaxy-halo connection [2]. One way to understand this relationship is to constrain the association between halo mass and stellar mass. Observing bright and massive galaxies has allowed astronomers to do this well for massive dark matter halos. However, the lowhalo-mass space is poorly constrained, owing to the difficulty of detecting faint galaxies.



The purpose of this project is to develop a deep-learning model trained on simulated LSBGs to detect faint objects in the data of the Dark Energy Survey (DES). We hope to train the model to find very large, diffuse features that are virtually undetectable in traditional source detection methods.

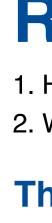
Methods

The model used is a variation of a Convolutional Neural Network (CNN) called Mask R-CNN [1]. We trained this model on images from the Dark Energy Survey containing two classes of objects: LSBGs (simulated) and artifacts (noisy compact sources). Images are preprocessed by removing compact sources, replacing them with a gaussian-distributed background, convolution with a gaussian kernel, and image binning.



Low-surface-brightness galaxies (LSBGs), defined as galaxies fainter than the night sky, inhabit this low halo mass space and thus detecting and constraining their properties is a key aspect in understanding dark matter.

Fig. 1 – Relationship between the ratio of stellar-to-halo mass and the total halo mass for central galaxies at zero redshift. The large-halomass region is well constrained due to the brightness of the galaxies that occupy these halos. The low-halo-mass region, surrounded by the red box where most models diverge, is poorly constrained and requires efficient ways for detecting low surface brightness galaxies to statistically distinguish between models.



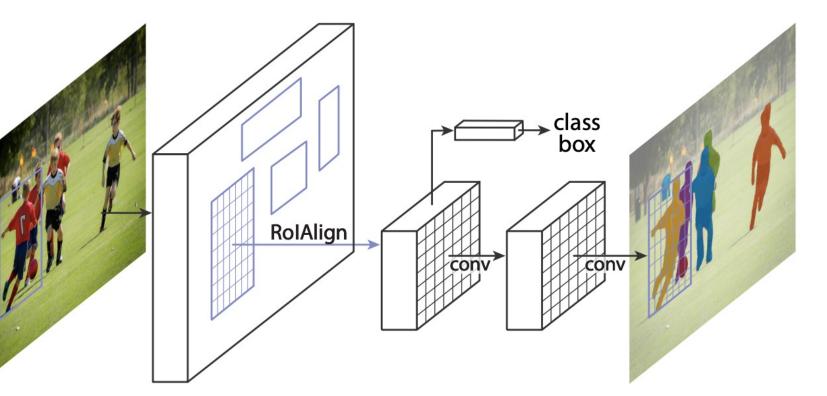
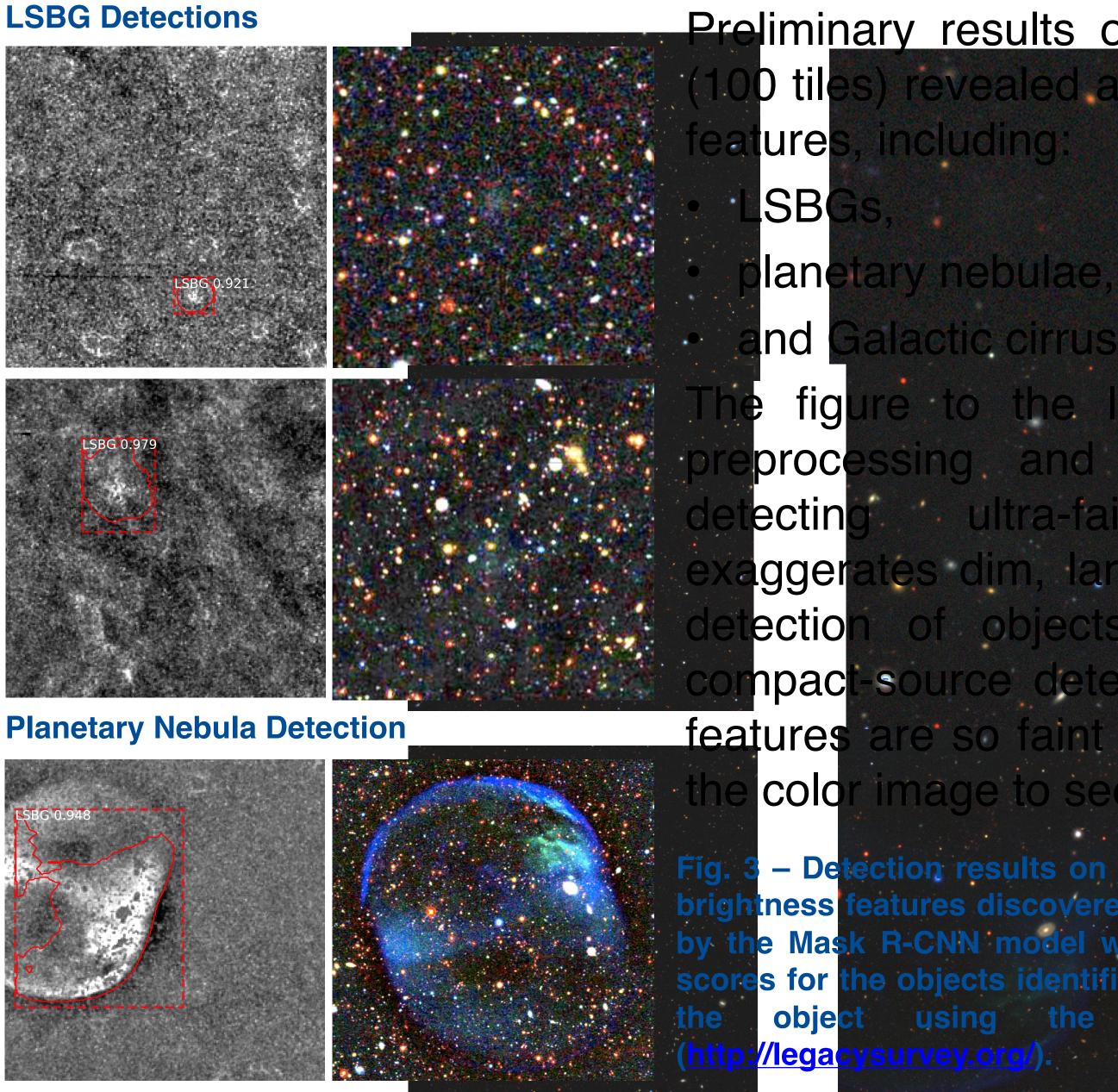


Fig. 2 – Object instance segmentation framework for the Mask R-CNN model. The model takes an image and first passes it to a pre-trained CNN, which outputs a feature map. This feature map is then fed into a region-proposal network that produces possible locations of objects. These regions are resized before being passed to the final stage of training where the network simultaneously learns to classify the object, find the optimum bounding box region, and create per-pixel associations with the class (masks).

Technical Training Info:	Technie
Processed 100 Tiles on DES cluster,	• Proc
~16 simulated LSBGs per tile	• Trar
Transferred to Google Drive	 Ran
Trained on Google Colab	• Gen
Used test set to evaluate model	visu

Results



References

1. He, K., Gkioxari, G., Dollár, P., Girshick, R., 2018. Mask R-CNN.1703.06870. 2. Wechsler, R.H., Tinker, J.L., 2018. The Connection Between Galaxies and Their Dark Matter Halos. ARA&A 56, 435–487. 1804.03097.

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ical Detection Info: cessed 10,000 tiles on DES cluster Insferred ~260GB to Google Drive n detection on Google Colab nerated webpage with detections for ual inspection

Preliminary results on 1% of the total DES dataset D tiles) revealed a variety of low surface brightness ft demonstrates the power of the Mask R-CNN model in Preprocessing objects. e-scale features and allows for not picked up by traditional tion algorithms. Some of these are so faint that they require high contrast of sample of DES data showing low surface The left panel shows the images outputted bounding boxes, masks, and confidence The right panel is a color image cutout of

ESI Legacy Imaging Sky Viewer