Alignment monitoring system for the PIP-II cryomodules FERMILAB-POSTER-20-029-TD

ALIGNMENT REQUIREMENTS

The alignment of the SSR1 cryomodule components was studied as the acceptable beam deflection, offset and defocusing, which may otherwise cause beam loss. Simulations and measurements established that the maximum deviations of the vacuum chamber from the reference orbit should not exceed 5% of the beam aperture.

	SSR1/HB650	Solenoid
Angular error RMS, [mrad]	< 10	< 1
Transverse error RMS, [mm]	< 1	< 0.5

PIP-II Technical Requirements Specification



SSR1 – Cavity Resonator

Solenoid – Focusing Lenses

ALIGNMENT STRATEGY

- Alignment monitoring through optical targets installed on the internal assembly
- The target position is observed by monitoring cameras (HBCAM), installed on the two outside ends of the cryomodule
- As a design choice we monitor only relative movements of the cryomodule components and have as a calibrated distance the difference between two glass balls.

MECHANICAL DESIGN

- Each SSR1 cryomodule includes eight cavities and four focusing lenses, with a total of 12 elements to be monitored.
- 96 glass balls are located in spatial distribution in order to not over shadow each over and allow full camera view of the target pattern
- The target tube is machined with rectangular slot and allow



glass balls being seen from both sides

The frame can be adjusted vertically as well as horizontally. Once the position established target frames are locked inside the survey base

MEASUREMENT PRINCIPLE

- Image reading on CCD sensors
- The camera measures the angular separation of two sources (high reflective index glass balls)

$\beta = d/r = s/c$

• c is the distance from the camera to the CCD sensor and is a calibrated distance • *d* is the separation between two targets, this must be a calibrated dimension









Cryomodule coldmass view





	x-axis		
	Nom	Mean	Var
Step size, [mm]	0.2	0.1981	0.0004
Relative error, [%]		1.25	0.84

Longitudinal distance [m]

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PERFORMANCES EVALUATION

- Targets mounted on translation stages, moving the transverse horizontal direction (*x-axis*)
- The results are validated through a CMM (Coordinate Measuring) Machine)

We observe a good agreement between the independent measurements of the HBCAM and the CMM, with sub-micrometric error on the x-axis.

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