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Ultimate 3D for a Pixel Detector - Tests of X-Rays Detection

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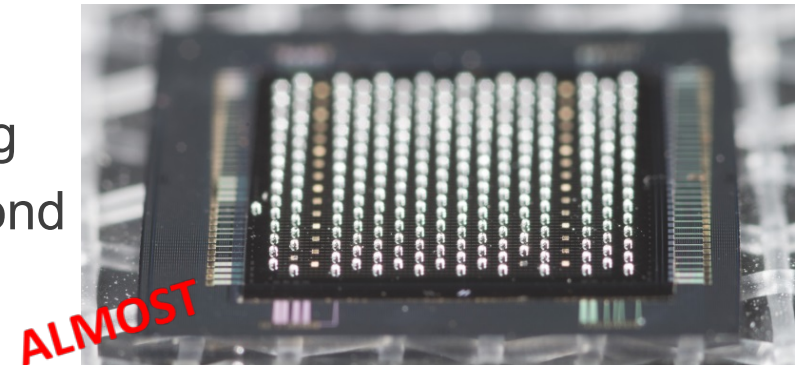
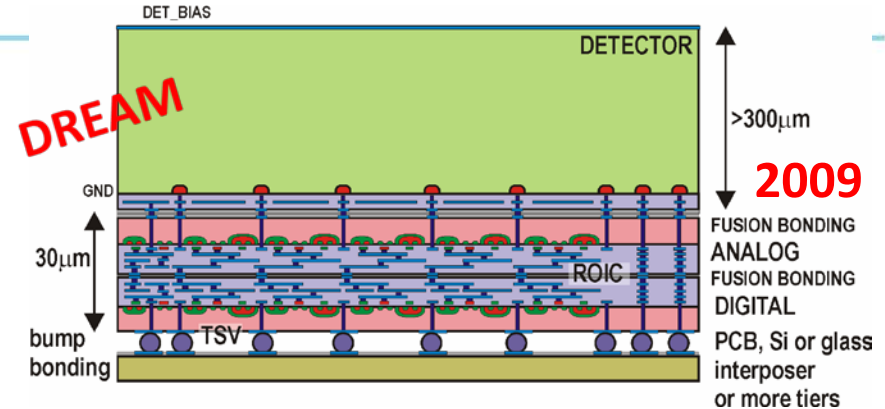
2014 IEEE NSS & MIC, Nov. 8 - 15, Seattle, WA USA

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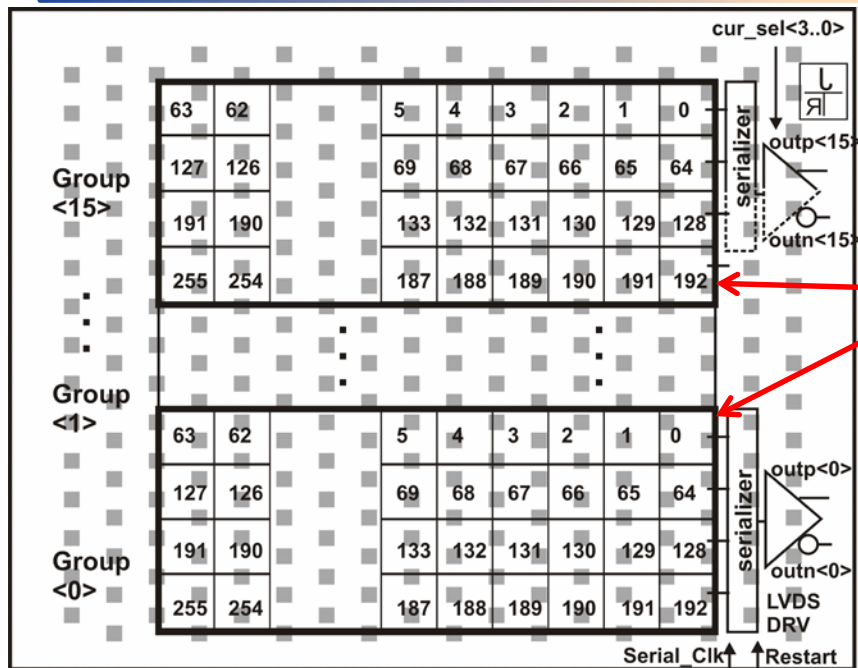
Outline:

- Ultimate 3D-integrated VIPIC1 chip structure
 - Update on 3D fabrication processing for VIPIC
 - W-2-W: ASIC stacking
 - D-2-D: sensor - ASIC b-bonding
 - D-2-W: ASIC - sensor fusion bond
 - D-2-PCB: 3D stack b-bonding
 - Test results of VIPIC
 - Fusion bonded
 - Front side illumination
 - Back side illumination
 - Ultimate b-bonded on PCB
- Conclusions



VIPIC1

VIPIC1 (prototype) counts hits in every pixel and reads out the # of hits, and pixel addresses in a dead timeless manner,



Active area: $5120 \times 5120 \mu\text{m}^2$, chip:
 $6.3 \times 5.5 \text{ mm}^2$

Matrix of 64×64 pixels divided into 16
group of 4×64 pixels read through
one LVDS buffer

Sparsification engine selects hit pixels
in every group for readout

Only digital information read out (~150
ns /hit pixel)

"Vertically Integrated Circuits at Fermilab", IEEE Transaction on Nuclear Science, vol. 57, no. 4, (2010), pp. 2178-2186

"VIPIC IC - Design and Test Aspects of the 3D Pixel Chip", Proceedings of NSS & MIC, Knoxville, TN, USA, October 2010

"Design and Tests of the Vertically Integrated Photon Imaging Chip", IEEE Trans. on Nuclear Sci., vol. 61, no. 1, (2014), pp. 663-674

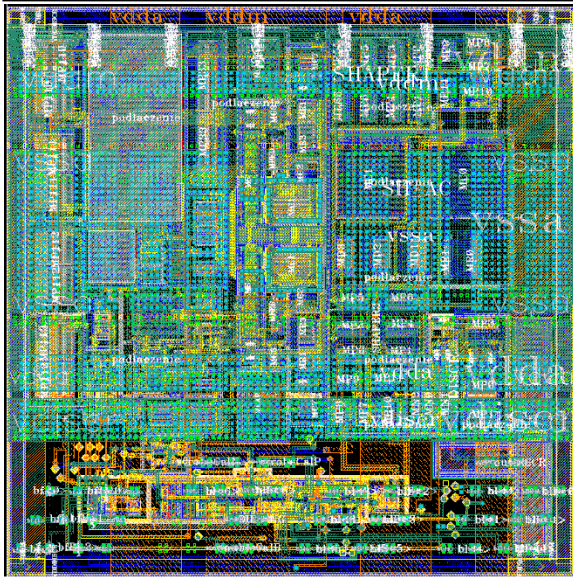
"Results of Tests of Three-Dimensionally Integrated Chips Bonded to Sensors", accepted for IEEE Transaction on Nuclear Science

"Recent Results for 3D Pixel Integrated Circuits Using Copper-Copper and Oxide-Oxide Bonding", PoS(VERTEX 2013)032

"Performance of Three Dimensional Integrated Circuits Bonded to Sensors", PoS(VERTEX 2014)XXX

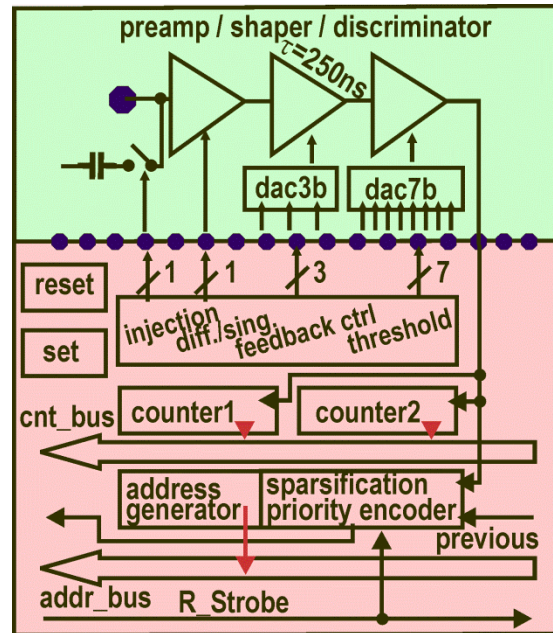
ANALOG

280 transistors



- ▶ Single ended or pseudo-differential CSA-shaping filter-discriminator – **design goals**:
shaping time $\tau_p = 250$ ns, power ~ 25 μ W / analog pixel, noise < 150 e^- ENC, gain ($C_{feed} = 8fF$) = ~ 100 mV/8keV (optimized for 8 keV in Si - linear up to 3×8 keV)
- ▶ 1 threshold discriminator
- ▶ 10 bit/pixel DAC adjustments

INTERFACE



12-bit for configuration

7-bit trim offset, 3-bit trim R_f , single/dif mode, CAL enable

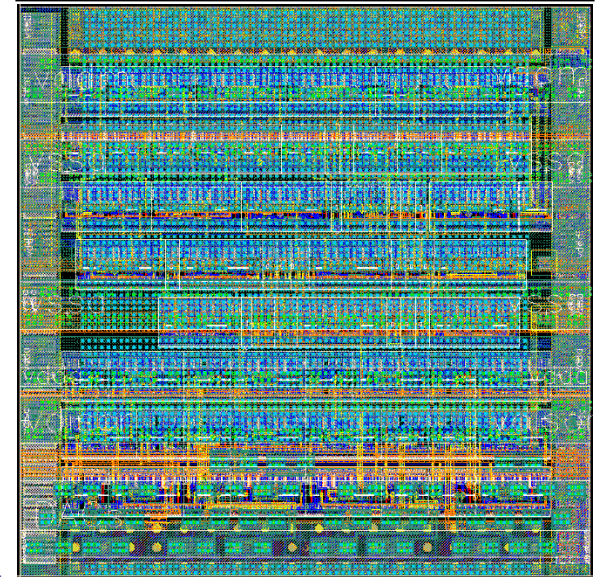
2-lines for CAL circuits

discriminator output

**Doubled bond pads
for each signal
Power supplies tied
between tiers**

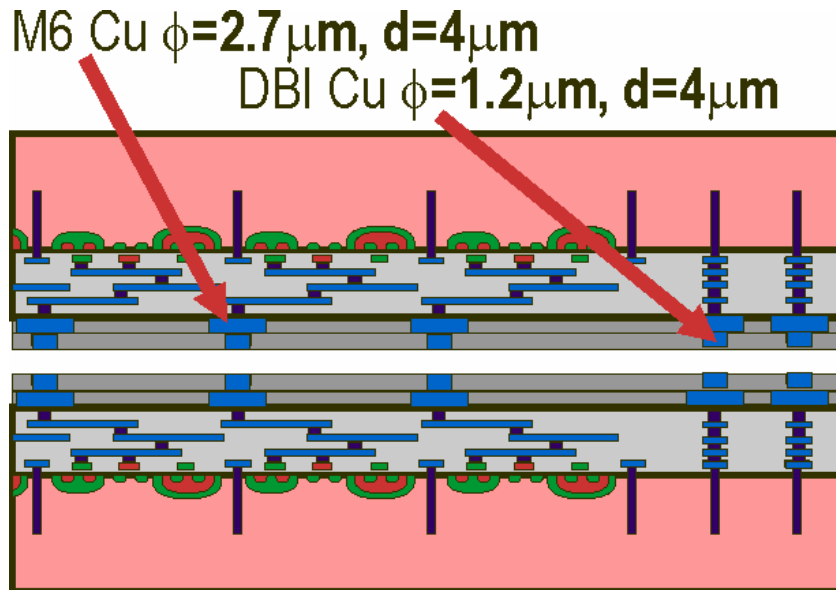
DIGITAL

1400 transistors



- ▶ in-pixel 1-stage pipe-line logic
- ▶ distributed sparsifier: 8 bit priority encoder, pixel readout selector, pixel address generator and counter output
- ▶ 2×5 - bit long counters
- ▶ configuration registers: single bit / pixel (pixel SET, pixel RESET) and 12 bit DAC and configuration (calib., singl./diff.)

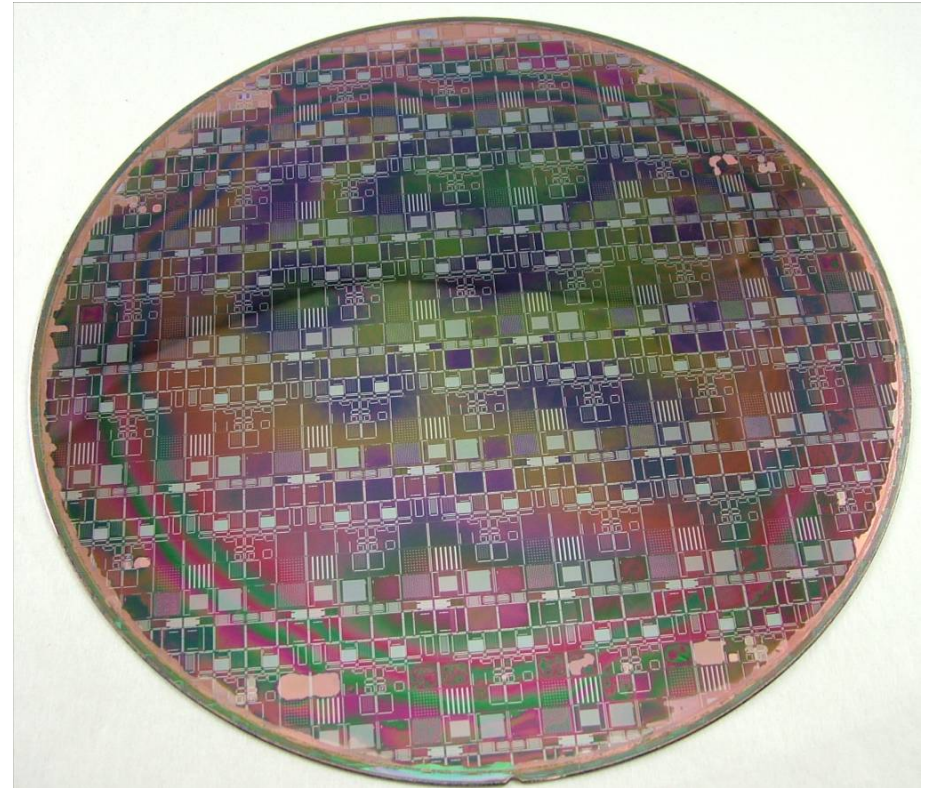
Processing: W-2-W ASIC stacking



Cu DBI

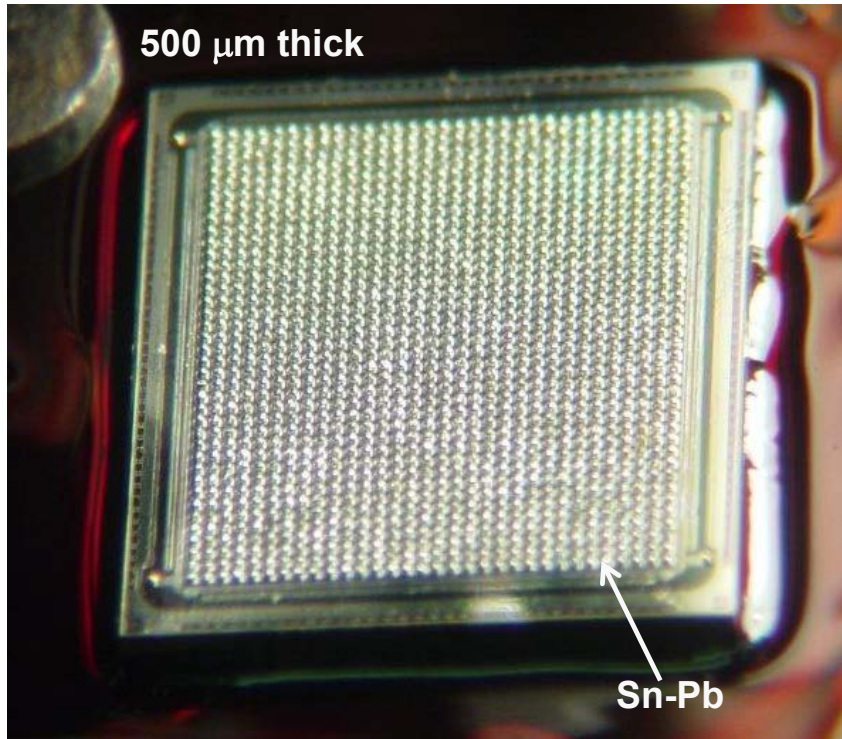
Cu-DBI (oxide-oxide fusion bonding)
used for bonding tiers of 3D VIPIC

- no pressure required and self propagating from initial contact point
- can be reworked for a short time after initial bonding

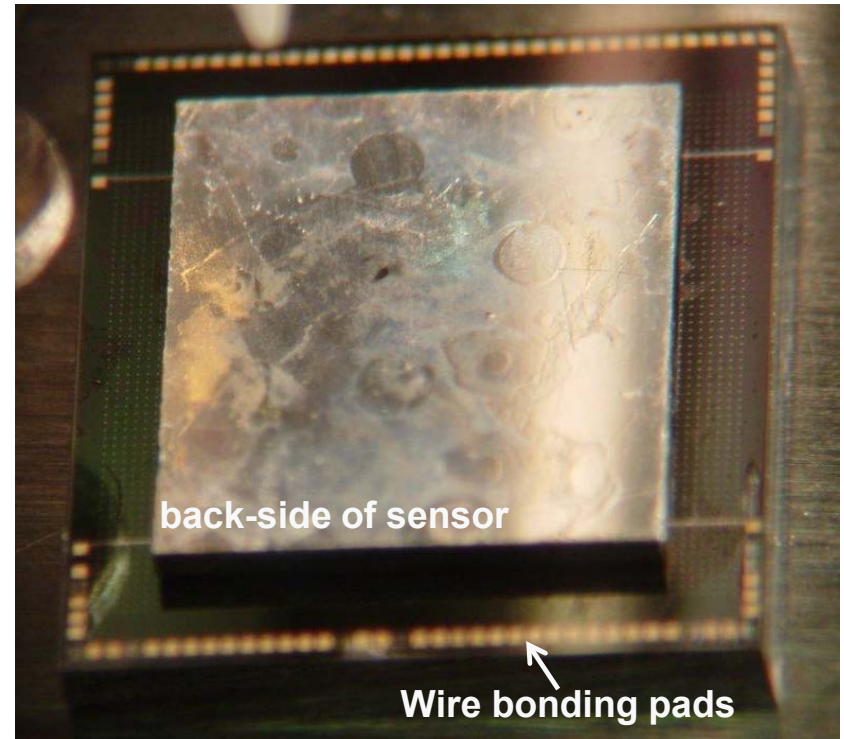


8" bonded wafer pair with top wafer thinned to expose $6\mu\text{m}$ TSVs ($6\mu\text{m}$ of silicon left of the top wafer)

Processing: D-2-D sensor - ASIC bump-bonding

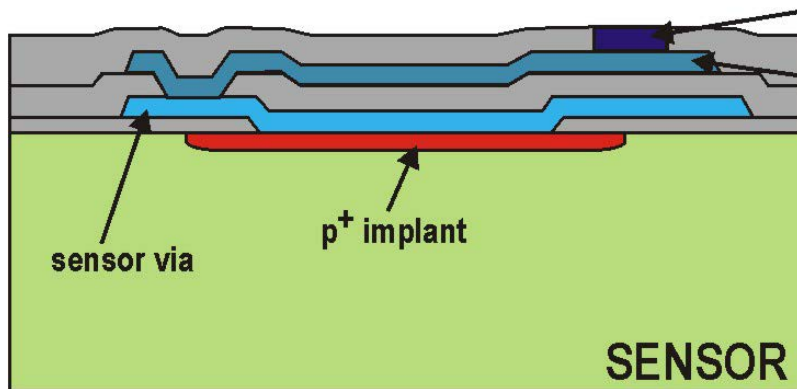
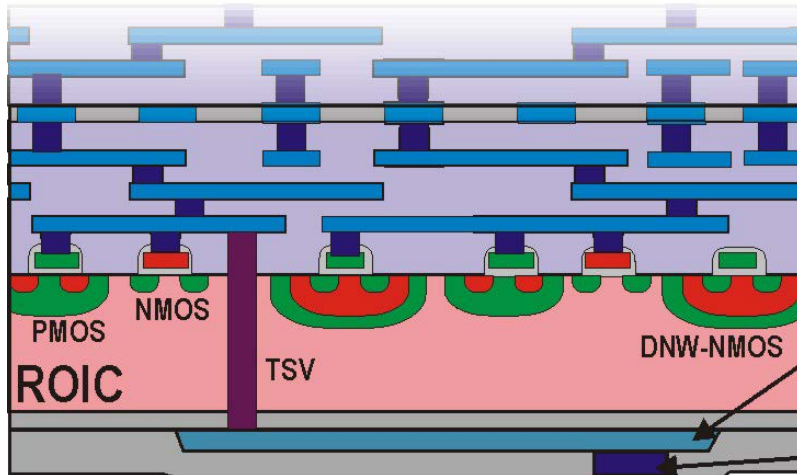


- ▶ 100 μm pitch HPK pixel baby-sensor
- ▶ Sn-Pb bumps deposition on a single die with ENIG UBM on Al substrate pads (by CVInc.) – pads $\phi=60 \mu\text{m}$
- ▶ UBM also deposited on VIPIC



- ▶ 300 μm thick baby-sensor on top of VIPIC (75 μm bump, post reflow gap at 45 μm to 50 μm prior to addition of underfill)
- ▶ Optimization of the Ni-Au deposition = ~100% of pads retaining UBM and bumps

Processing: D-2-W ASIC - sensor fusion bonding

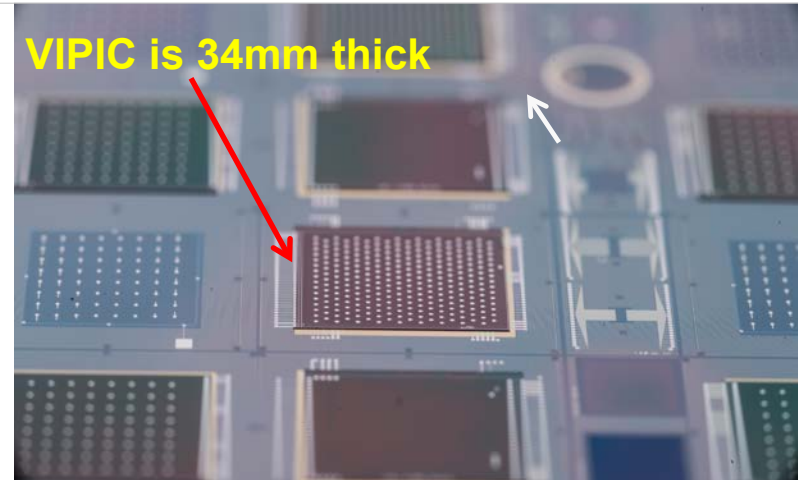


Ni-DBI (oxide-oxide fusion bonding) with DBI post $\phi=5$ mm,

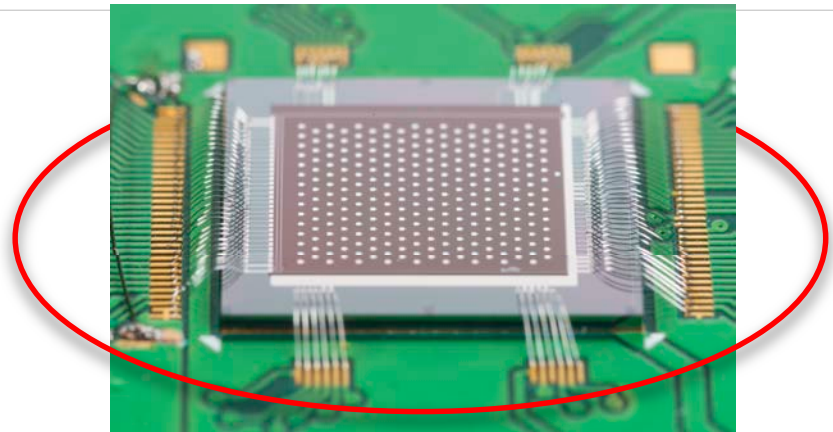
top-2-bottom: 50nm nitride, 1 μ m oxide, 300nm Al, 1 μ m oxide + 700nm DBI and 700nm DBI + 1 μ m oxide, 300nm Al, 1 μ m oxide, 300nm thermal oxide

die on 6" 500 μ m thick sensor wafer

VIPIC is 34mm thick



allows back and front -side illumination



Processing: D-2-PCB 3D stack b-bonding

VIPIC
with
Sn-Pb
bumps

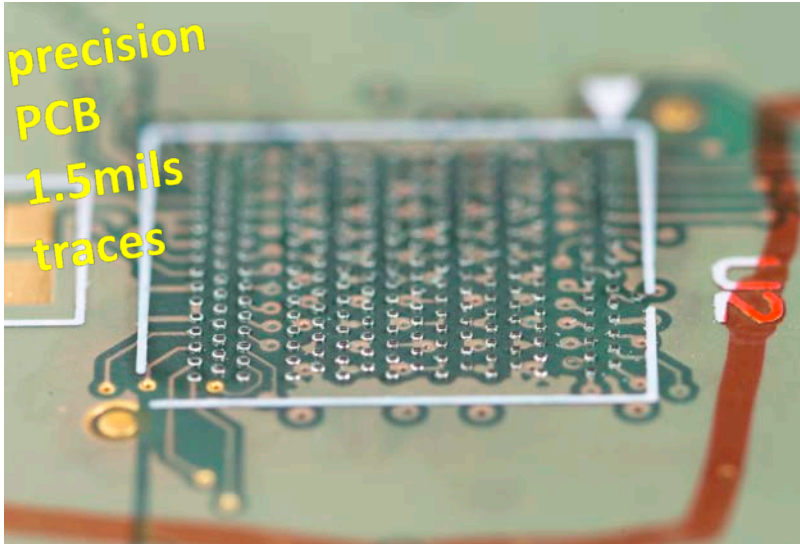


Sn-Pb bumps deposition on a single 3D assembly with ENIG UBM on Al substrate pads (by CVInc.)

- square pads $a=100\text{ }\mu\text{m}$, 279 pads on $320\mu\text{m}$ pitch (staggered layout)
- challenge for design on FR-4 PCB 1.5 mils traces (it would be easier on ceramic or on silicon interposer - future)

'ultimate 3D VIPIC1'

precision
PCB
1.5mils
traces



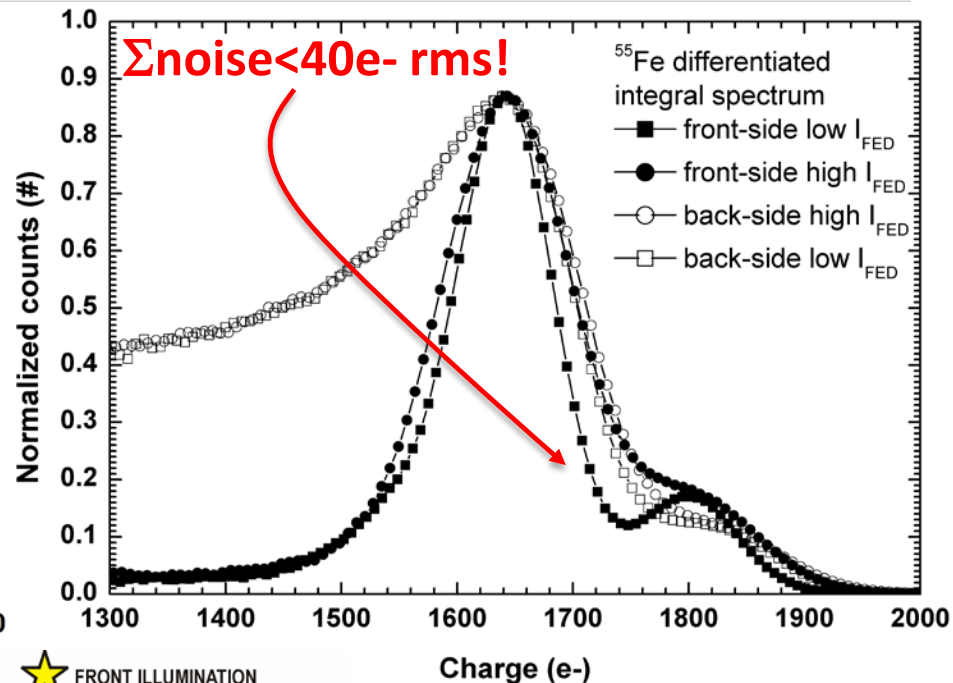
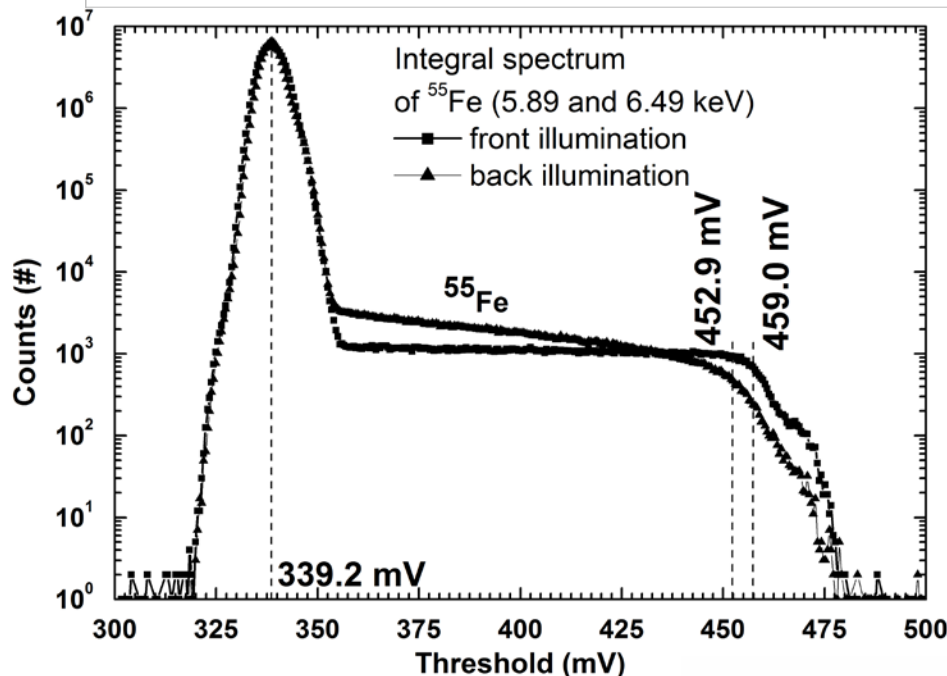
VIPIC
on PCB
sensor
up



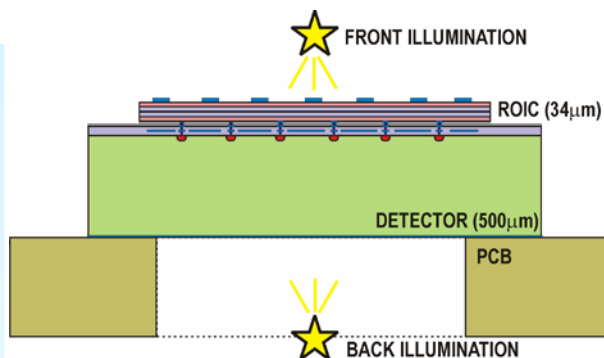
underfill epoxy to stabilize VIPIC on flexing substrate

Results: reference X-ray source spectra

thin die and access through traces on sensor → front and back illumination



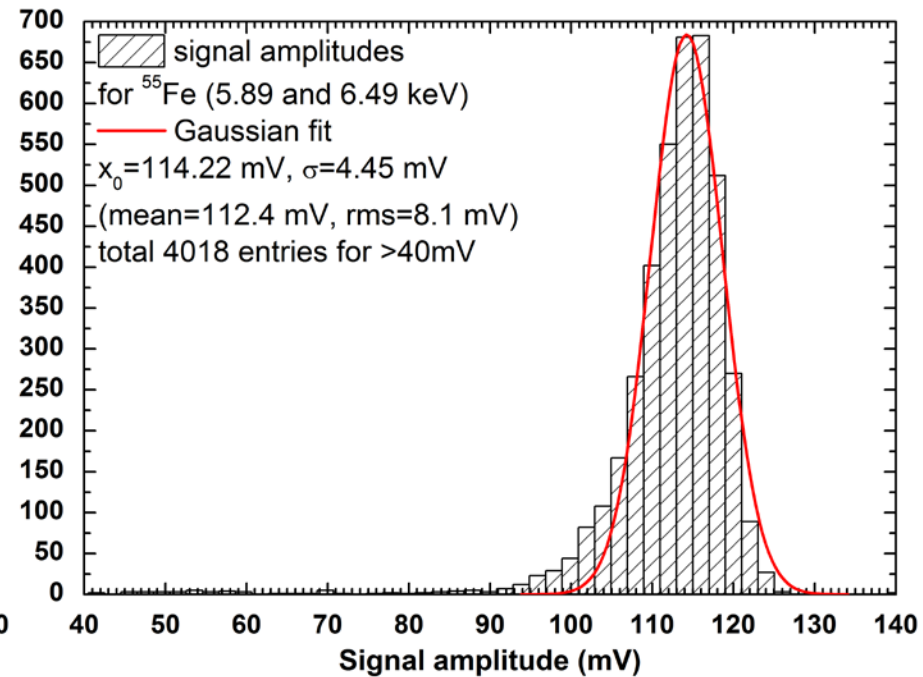
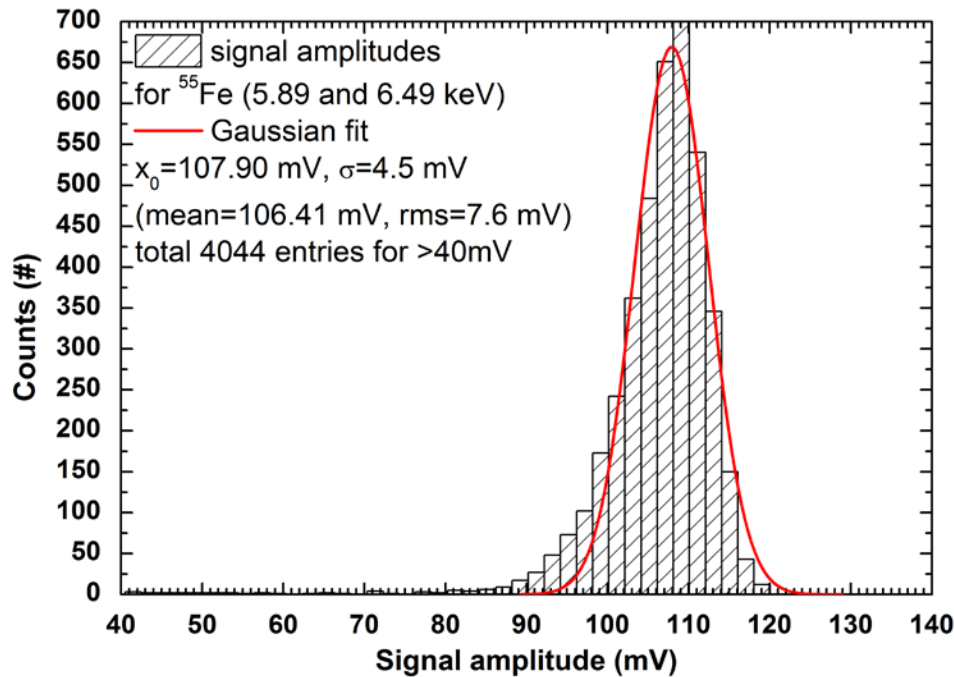
integral E spectra of ^{55}Fe
front and back illumination of
500 μm thick fully depleted
($V_{\text{dep}}=170\text{V}$) Si sensor with
fusion bonded VIPIC1
(threshold scan @ $\Delta V=500\mu\text{V}$)



E spectra of ^{55}Fe
(amplitudes scaled to expected
spectral peaks)
front and back illumination
with varied resistances in
feedback of preamplifier

Results: gain* from reference X-ray source

back and front illumination



BACK ILLUMINATION

Q-2-V gain = $65.18 \mu\text{V}/e^- \pm 2.74 \mu\text{V}/e^-$
<1.3 % of pixels not connected or having
lower gain for other reasons

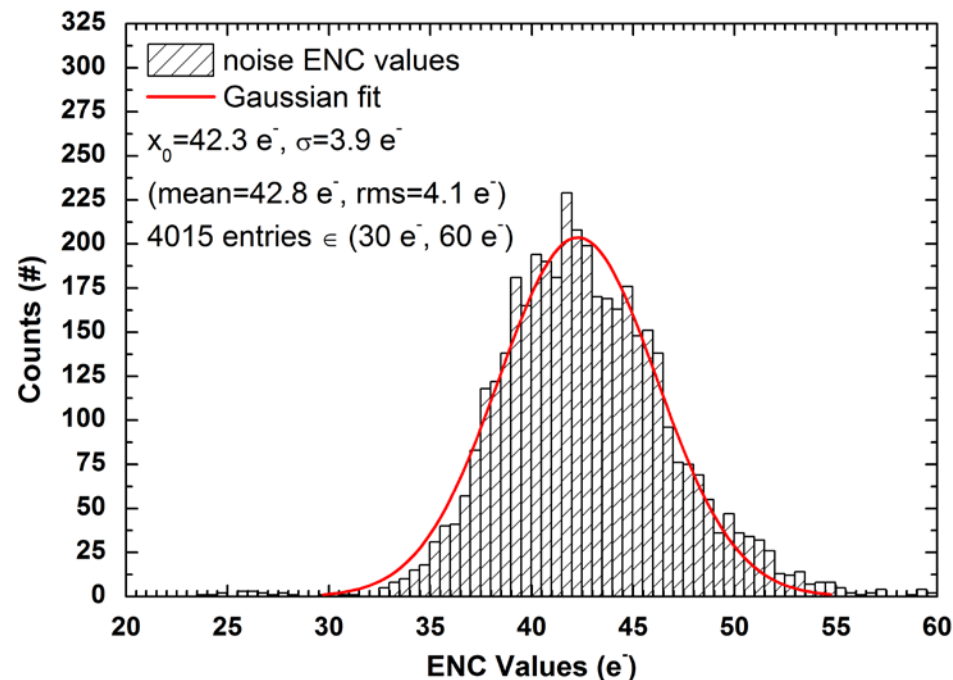
FRONT ILLUMINATION

Q-2-V gain = $69.64 \mu\text{V}/e^- \pm 2.71 \mu\text{V}/e^-$
<1.9 % of pixels not connected or having
lower gain for other reasons

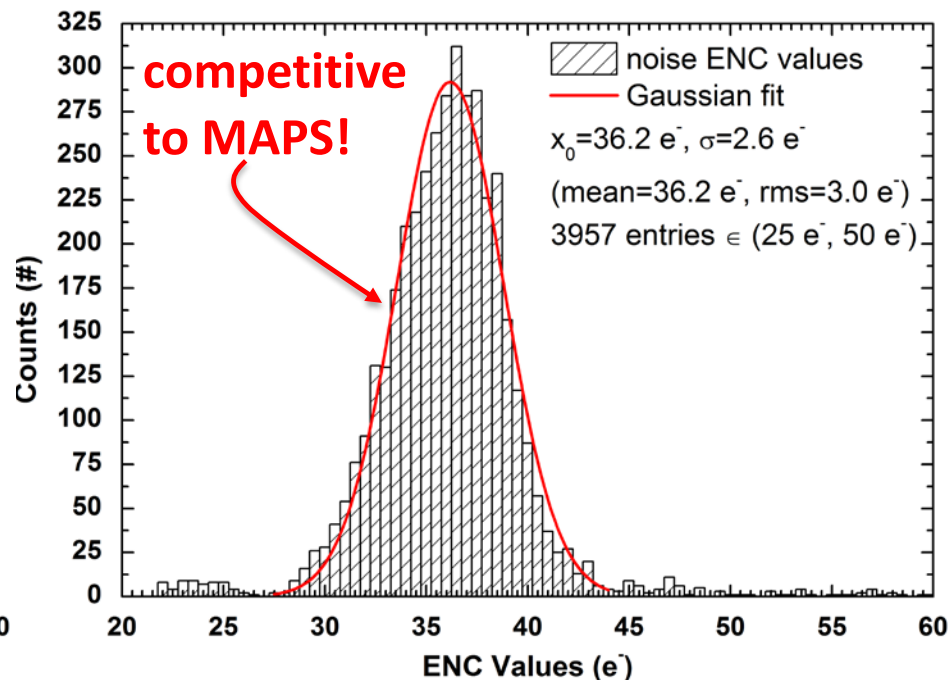
*gain calculated through adaptive procedure of numerical differentiation of integral spectra

Results: noise from calibrated gain

front illumination with small and large feedback resistance in preamplifier



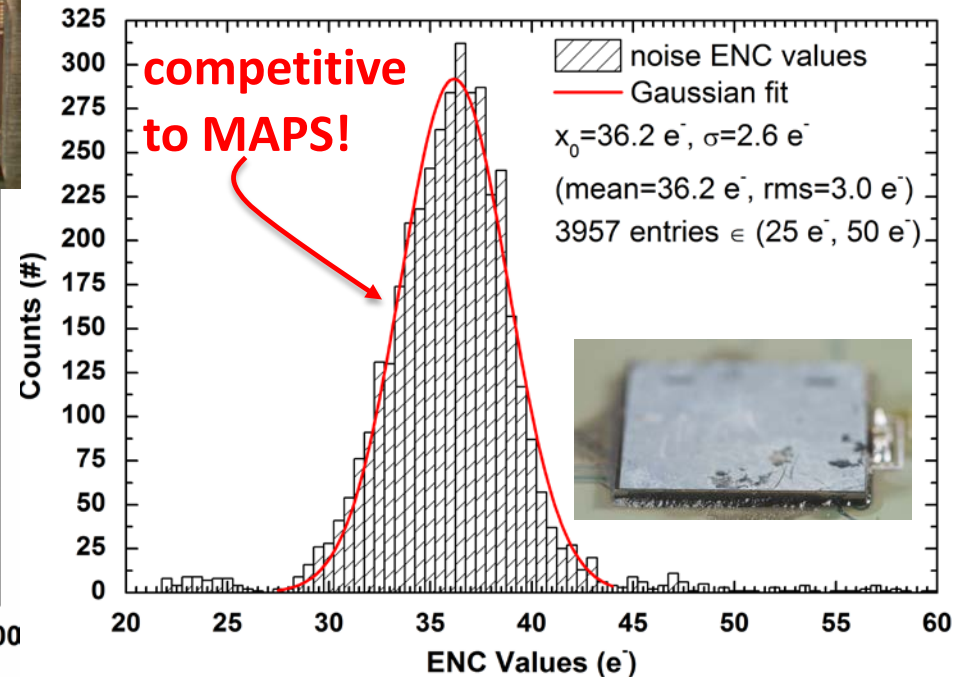
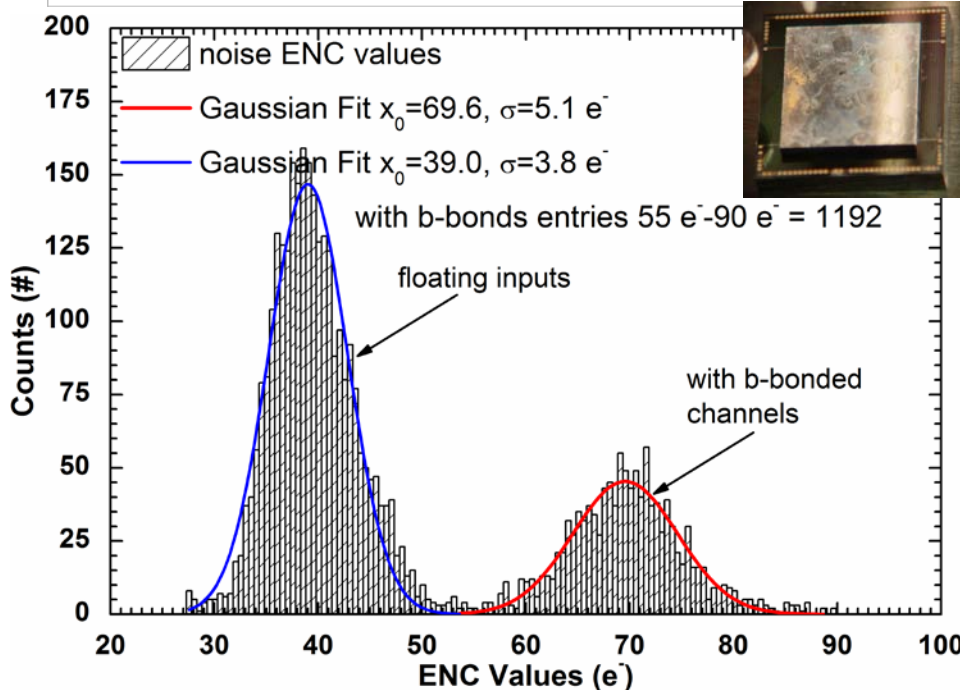
SMALL FEEDBACK RESISTANCE
 $\text{ENC} = 42.3 \text{ e}^- \pm 3.9 \text{ e}^-$
symmetrical noise distribution with
<1.9 % of pixels outside of $\pm 3 \sigma$ range



LARGE FEEDBACK RESISTANCE
 $\text{ENC} = 36.2 \text{ e}^- \pm 2.6 \mu\text{V/e}^-$
symmetrical noise distribution with
<3.4 % of pixels outside of $\pm 3 \sigma$ range

Results: noise comparison fusion-bonded vs bump-bonded

Bump-bonded VIPIC1 pitch 100 μ m vs. 80 μ m for fusion-bonded, nevertheless ...



32 \times 38 pixels bonded, 2880 pixels floating
bump-bonded: ENC=69.6 e $^-$ \pm 5.1 μ V/e $^-$
larger input capacitance = larger noise,
lower gain and more dispersions

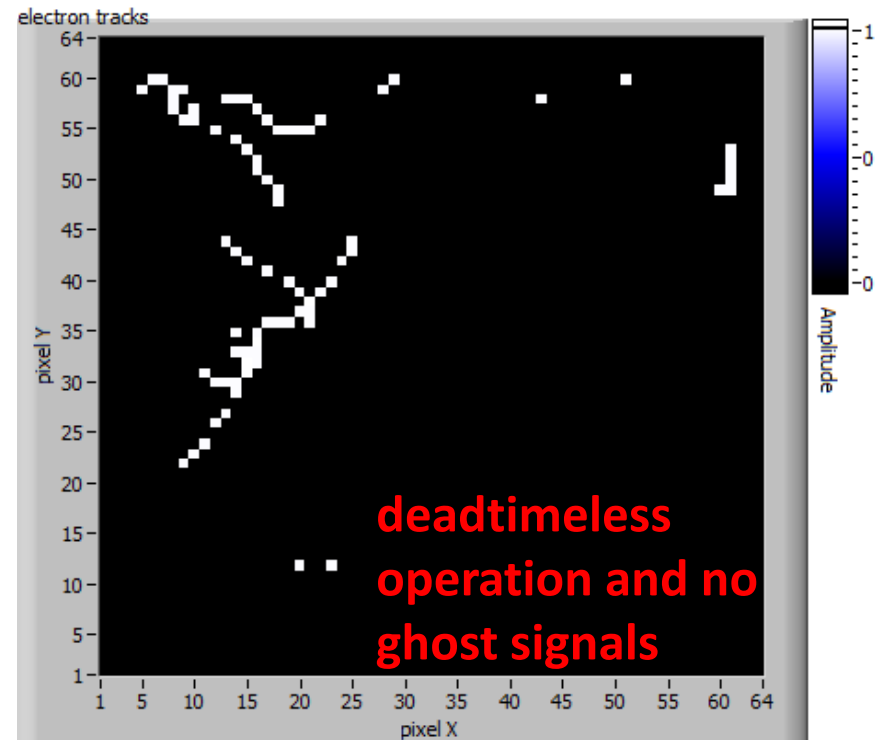
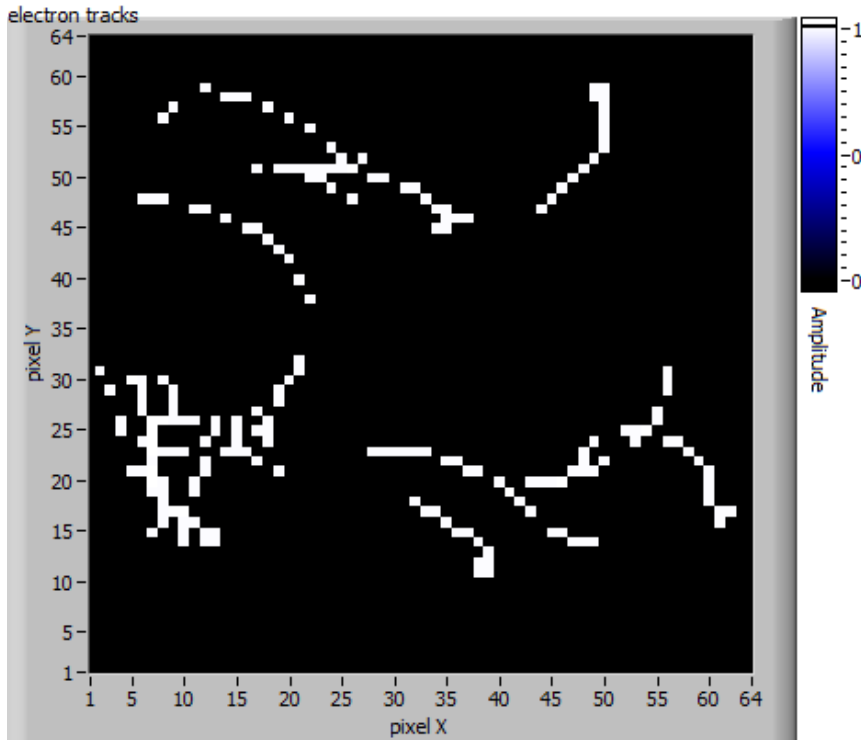
LARGE FEEDBACK RESISTANCE
ENC=36.2 e $^-$ \pm 2.6 μ V/e $^-$
symmetrical noise distribution with
<3.4 % of pixels outside of $\pm 3 \sigma$ range

ENC on fusion bonded device is close to that measured for floating inputs!

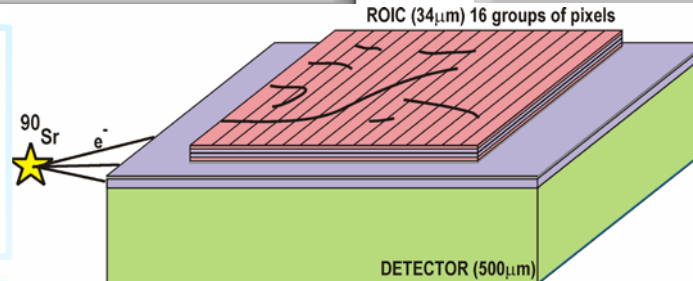
ENC=40e $^-$ C_{in} <20fF, ENC=70e $^-$ C_{in} >80fF

Sparsified readout

tracks of 0.546 MeV (endpoint) electrons from ^{90}Sr in fully depleted ($V_{\text{dep}}=170\text{V}$) Si sensor with fusion bonded VIPIC1 (perpendicular to groups)



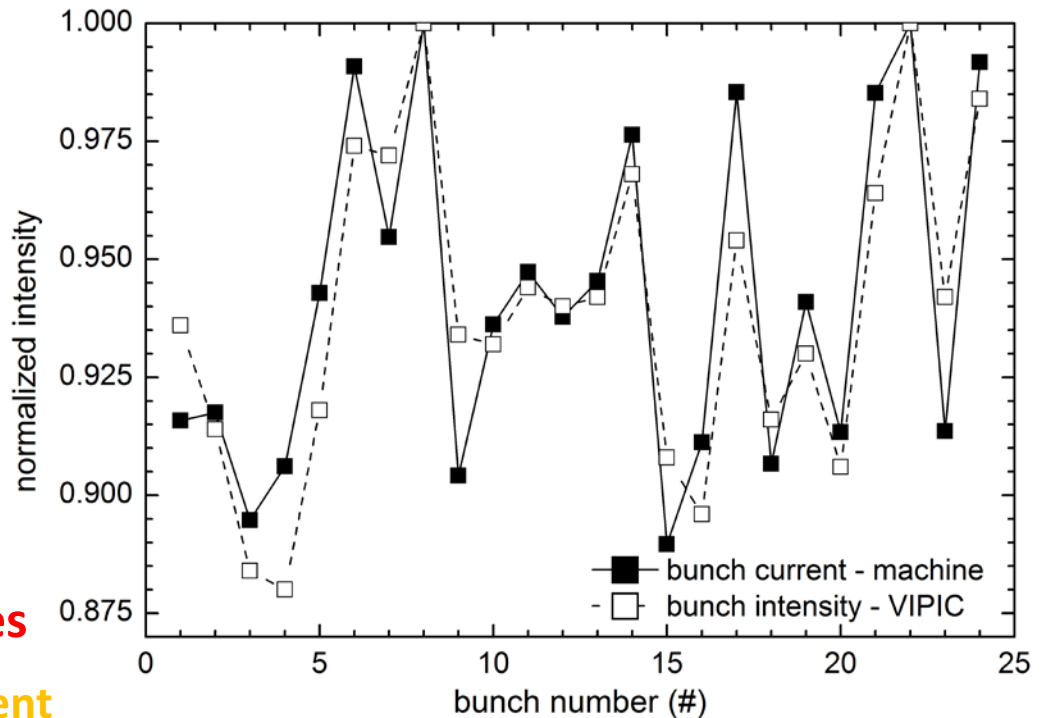
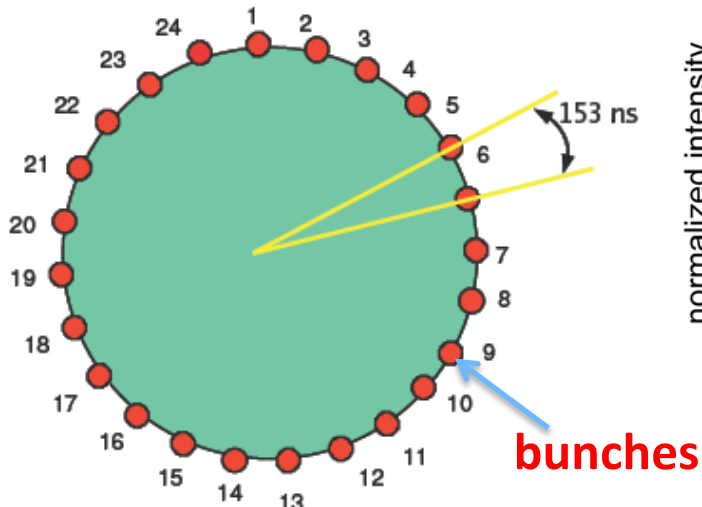
Superposition of selected 13 frames acquired @ $\Delta t=2.7\mu\text{s}$ (max. 24 hits/group)



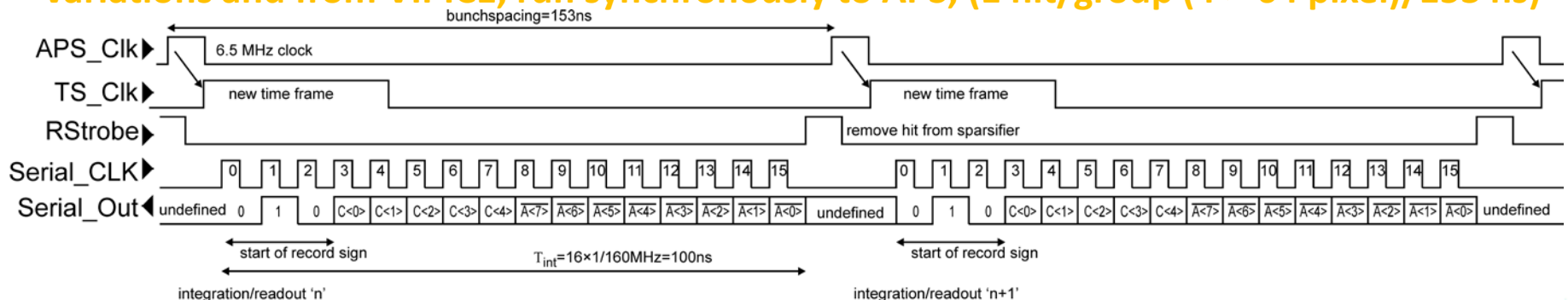
Superposition of 13 frames; each frame is directly next to the respective one used to the left.

Results: APS 10keV X-ray beam

fill pattern: 24 bunches spaced by 153ns, tests with direct beam on 'ultimate 3D VIPIC1'



X-ray intensity from b-b e^- beam current variations and from VIPIC1, run synchronously to APS, (1 hit/group (4×64 pixel)/153 ns)



Conclusions

- **Conclusive demonstration of the capabilities of 3D technology applied to pixel detectors has been reached!**
- Shown parameters are better than for bump-bonded devices and competitive with MAPS (in term of noise).
- Analyses of data from XCS experiments performed in July and October 2014 are underway (first capture of samples' dynamics on a scale of tens of μs with a 2D detector)
- BES funded project (3 labs collaboration BNL-FNAL-ANL) to build a 1M-pixel camera for XCS experiments using 3D-IC technology
- Acknowledgments: Alec Sandy, Eric Dufresne, Suresh Narayanan, John Weizeorick, David Kline (beam tests at the APS at ANL); many thanks to Albert Dyer (board assembly)

- Tezzaron and Ziptronix, as the 3D technology providers.
- The greatness of 3D-IC consortium (17 partners from USA, France, Italy, Germany, Poland and Canada), enthusiasm and exchange of information for common goals were fundamental.

