A Transport-Friendly NIC for Multicore/Multiprocessor Systems

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Abstract - Receive side scaling (RSS) is a network interface card (NIC) technology. It provides the benefits of parallel receive processing in multiprocessing environments. However, existing RSS-enabled NICs lack a critical data steering mechanism that would automatically steer incoming network data to the same core on which its application process resides. This absence causes inefficient cache usage if an application is not running on the core on which RSS has scheduled the received traffic to be processed and results in degraded performance. To remedy the RSS limitation, Intel’s Ethernet Flow Director technology has been introduced. Flow Director steers packets of a specific data flow to the same core on which its application process resides. However, our analysis and experiments show that Flow Director can cause significant packet reordering in multiprocessing environments.

In this paper, we propose a NIC mechanism to remedy the RSS and Flow Director limitations. It steers incoming network data to the same core on which its application resides and ensures inorder packet delivery. This data steering mechanism is mainly targeted at TCP, but it can be extended to other transport layer protocols. We term a NIC with such a data steering mechanism “A Transport Friendly NIC” (A-TFN). Experimental results have proven the effectiveness of A-TFN in accelerating TCP/IP performance.


1. Introduction & Motivation

Computing is shifting towards multiprocessing (e.g., SMT, CMP, SMP, and UNMA). The fundamental goal of multiprocessing is improved performance through the introduction of additional hardware threads, CPUs, or cores (all of which will be referred to as “cores” for simplicity). The emergence of multiprocessing has brought both opportunities and challenges for TCP/IP performance optimization in such environments. Modern network stacks can exploit parallel cores to allow either message-based parallelism or connection-based parallelism as a means of enhancing performance [1]. To date, major network stacks such as Windows, Solaris, Linux, and FreeBSD have been redesigned and parallelized to better utilize additional cores. While existing OSes exploit parallelism by allowing multiple threads to carry out network operations concurrently in the kernel, supporting this parallelism carries significant costs, particularly in the context of contention for shared resources, software synchronization, and poor cache efficiencies [2][3]. However, various optimization efforts, such as fine-grained locking and the read-copy-update technologies, have been helpful. While these optimizations definitely help improve TCP/IP processing in multiprocessing environments, they alone are not sufficient to keep pace with network speeds. A scalable, efficient network I/O in multiprocessing environments requires further optimization and coordination across all layers of the network stack, from network interface to application. Investigations regarding processor affinity [4][5][6][7] indicate that the coordinated affinity scheduling of protocol processing and network applications on the same target cores can significantly reduce contention for shared resources, minimize software synchronization overheads, and enhance cache efficiency.

Coordinated affinity scheduling of protocol processing and network applications on the same target cores has the following goals: (1) Interrupt affinity, network interrupts of the same type should be directed to a single core. Redistributing network interrupts in either a random or round-robin fashion to different cores has undesirable side effects [6]. (2) Flow affinity, packets of each flow should be processed by a single core. Flow affinity is especially important for TCP. TCP is a connection-oriented protocol, and it has a large and frequently accessed state that must be shared and protected when packets from the same connection are processed. Ensuring that all packets in a TCP flow are processed by a single core reduces contention for shared resources, minimizes software synchronization, and enhances cache efficiency. (3) Network data affinity, incoming network data should be steered to the same core on which its application process resides. This is becoming more important with the advent of Direct Cache Access (DCA) [8][9]. DCA is a NIC technology that seeks to directly place a received packet into a core’s cache for immediate access by the protocol stack and application. Network data affinity maximizes cache efficiency and reduces core-to-core synchronization. In a multicore system, the function of network data steering is executed by directing the corresponding network interrupts to a specific core (or cores).

RSS [10] is a NIC technology. It supports multiple receive queues and integrates a hashing function in the NIC. The NIC computes a hash value for each incoming packet. Based on hash values, NIC assigns packets of the same data flow to a single queue and evenly distributes traffic flows across queues. With Message Signal Interrupt (MSI/MSI-X) [11] support, each receive queue is assigned a dedicated interrupt and RSS steers interrupts on a per-queue basis. RSS provides the benefits of parallel receive processing in multiprocessing environments. Operating systems like Windows, Solaris, Linux, and FreeBSD now support interrupt affinity. When an RSS receive queue (or interrupt) is tied to a specific core, packets from the same flow are steered to that core (Flow pinning [12]). This ensures flow affinity on most OSes, except for Linux (see Section 2).

However, RSS has a limitation: it cannot steer incoming network data to the same core where its application process resides. The reason is simple: the existing RSS-enabled NICs
do not maintain the relationship “Traffic Flows → Network applications → Cores” in the NIC (since network applications run on cores, the most critical relationship is simply “Traffic Flows → Cores (Applications)”) and the existing OSes do not support such capability. This is symptomatic of a broader disconnect between existing software architecture and multicore hardware. On OSes like Windows, if an application is not running on the core on which RSS has scheduled the received traffic to be processed, network data affinity cannot be achieved, resulting in degraded cache efficiency [10]. This limitation might cause serious performance degradation for NUMA systems. Furthermore, On OSes like Linux, if an application runs on cores other than those where its corresponding RSS network interrupts are directed, Linux TCP processing might alternate between different cores even if the interrupts for the flow are pinned to one core [see Section 2]. There will be neither flow affinity, nor network data affinity. As a result, it will lead to poor cache efficiency and cause significant core-to-core synchronization overheads. The overall system efficiency could be severely degraded.

The NIC technologies, such as Intel’s VMDq [27] or the PCI-SIG’s SR-IOV [28], do provide data steering capabilities for the NICs. But they are I/O virtualization technologies targeting at virtual machines in the virtualized environment, not targeting at general purpose OSes.

In parallel to our research, Intel has introduced the Ethernet Flow Director technology [13]. The basic idea is simple: Flow Director maintains the relationship “Traffic Flows → Cores (Applications)” in the NIC. OSes are correspondingly enhanced to support such capability. Flow Director not only provides the benefits of parallel receive processing in multiprocessing environments, it also can automatically steer packets of a specific data flow to the same core, where they will be protocol-processed and finally consumed by the application. However, our analysis and experiments show that Flow Director can cause significant packet reordering in multiprocessing environments. TCP performance suffers in the event of severe packet reordering.

In this paper, we propose a NIC mechanism to remedy the RSS and Flow Director limitations. It steers incoming network data to the same core on which its application resides and ensures in-order packet delivery. Our data steering mechanism is mainly targeted at TCP, but can be extended to UDP and SCTP. We term a NIC with such a data steering mechanism A Transport-Friendly NIC, or A-TFN. As Flow Director, A-TFN maintains the relationship “Traffic Flows → Cores (Applications)” in the NIC, with OSes correspondingly enhanced to support such capability. For transport layer traffic, A-TFN maintains a Flow-to-Core table in the NIC, with one entry per flow. Each entry tracks which receive queue (core) a flow should be assigned to. However, A-TFN is different from Flow Director in two significant ways:

1. They differ in the method of updating the Flow-to-Core table in the NIC. A-TFN makes use of the facts that TCP connections always involve packets flowing in both directions (ACKs, if nothing else). And when an application makes socket-related system calls, that calling application’s context would be borrowed to carry out network processing in process context. With each outgoing transport-layer packet, the OS records a processor core ID and uses it to update the entry in the Flow-to-Core table. As soon as any network processing is performed in a process context, A-TFN learns of the core on which an application process resides and can steer future incoming traffic to the right core. As for Flow Director, it requires that OS must be multiple TX queue capable [14]. Each core in the system is assigned a specific transmit queue. Outgoing traffic generated on a specific core is transmitted via its corresponding transmit queue. For an outgoing transport-layer packet, the OS records the transmit queue ID (processing core ID) and use it to update the corresponding entry in the NIC.

2. A-TFN has a mechanism to ensure in-order packet delivery. Flow Director does not have such a mechanism. Our analysis and experiments show that Flow Director can cause significant packet reordering in multiprocessing environments.

Clearly, to design A-TFN, there is an obvious trade-off between the amount of work done in the NIC and in the OS. In the paper, we discuss two design options. Option 1 is to minimize changes in the OS and focuses instead on identifying the minimal set of mechanisms to add to the NIC. This design adds complexity and cost to the NIC. On the other end of the design space, it could be let the OS update the flow-to-core table directly without changing anything in the NIC hardware (option 2). Conceptually, this approach could be fairly straightforward to implement. However, it might add significant extra communication overheads between the OS and the NIC, especially when the Flow-to-Core table gets large. Due to space limitation, this paper is mainly focused on the first design option. The new NIC is emulated in software and it shows that the solution is effective and practical to remedy the limitations in RSS and Flow Director. In future work, we will explore the second design option.

The contributions of this paper are fourfold. First, we show for certain OSes, such as Linux, that tying a traffic flow to a single core does not necessarily ensure flow affinity or network data affinity. Second, we show that existing RSS-enabled NICs lack a mechanism to automatically steer packets of a data flow to the same core(s), where they will be protocol-processed and finally consumed by the application. This is symptomatic of a broader disconnect between existing software architecture and multicore hardware. Third, our analysis and experiments show that Flow Director can cause significant packet reordering in multiprocessing environments. It lacks a mechanism to ensure in-order packet delivery. Fourth, we propose a NIC mechanism to remedy the limitations in RSS and Flow Director. It steers incoming network data to the same core on which its application resides and ensures in-order packet delivery.

The remainder of the paper is organized as follows: In Section 2, we present problem formulation. Section 3 describes the A-TFN mechanism. In section 4, we discuss experiment results that showcase the effectiveness of our A-
TFN mechanism. In section 5, we present related research. We conclude in section 6.

2. Problem Formulation

2.1 Packet Receive Processing with RSS

RSS is a NIC technology. It supports multiple receive queues and integrates a hashing function in the NIC. NIC computes a hash value for each incoming packet. Based on hash values and an indirection table, NIC assigns packets of the same data flow to a single queue and evenly distributes traffic flows across queues. With Message Signal Interrupt (MSI/MSI-X) and Flow Pinning support, each receive queue is assigned a dedicated interrupt and tied to a specific core. The device driver allocates and maintains a ring buffer for each receive queue within system memory. For packet reception, a ring buffer must be initialized and pre-allocated with empty packet buffers that have been memory-mapped into the address space that is accessible by the NIC over the system I/O bus. The ring buffer size is device- and driver-dependent. Fig. 1 illustrates packet receive-processing with RSS: (1) When incoming packets arrive, the hash function (e.g., Toeplitz hashing [10]) is applied to the header to produce a hash result. The hash type, which is configurable, controls which incoming packet fields are used to generate the hash result. OSes can enable any combination of the following fields: source address, source port, destination address, destination port, and protocol. The hash mask is applied to the hash result to identify the number of bits that are used to index the indirection table. The indirection table is the data structure that contains an array of core numbers to be used for RSS. Each lookup from the indirection table identifies the core and hence, the associated receive queue. (2) The NIC assigns incoming packets to the corresponding receive queues. (3) The NIC DMAs (direct memory access) the received packets into the corresponding ring buffers in the host system memory. (4) The NIC sends interrupts to the cores that are associated with the non-empty queues. Subsequently, the cores respond to the network interrupts and process received packets up through the network stack from the corresponding ring buffers one by one.

The OS can periodically rebalance the network load on cores by updating the indirection table, based on the assumption that the hash function will evenly distribute incoming traffic flows across the indirection table entries. Since the OS does not know which specific entry in the indirection table an incoming traffic flow will be mapped to, it can only passively react to load imbalance situations by changing each core’s number of appearances in the indirection table. For better load balancing performance, the size of the indirection table is typically two to eight times the number of cores in the system [10]. For example, in Fig. 1, the indirection table has 8 entries, which are populated as shown. As such, traffic loads directed to Core 0, 1, 2, and 3 are 50%, 25%, 12.5%, and 12.5%, respectively. Some OSes like Linux and FreeBSD do not support the function of an indirection table; the incoming packets are directly mapped to the receive queues. These OSes cannot perform dynamic load balancing.

The reason is simple: the existing RSS-enabled NICs do not maintain the relationship “Traffic Flows → Network applications → Cores” in the NIC (since network applications run on cores, the most critical relationship is simply “Traffic Flows → Cores (Applications).”) and the existing OSes do not support such capability. When packets arrive, the hash function is applied to the header to produce a hash result. Based on the hash values, the NIC assigns packets to receive queues and then cores, with no way to consider on which core the corresponding application is running. Although receive queues can be instructed to send interrupt to a specific set of cores, existing general purpose OSes can only provide limited process-to-interrupt affinity capability; network interrupt delivery is not synchronized with process scheduling. This is because the OS schedulers have other priorities, such as load balancing and fairness, over process-to-interrupt affinity. Besides, multiple network applications’ traffic might map to a single interrupt, which brings new challenges to an OS scheduler. Therefore, a network application might be scheduled on cores other than those where its corresponding network interrupts are directed. This is symptomatic of a broader disconnect between existing software architecture and multicore hardware.

OSes like Windows implement the function of the indirection table, which can provide limited data steering capabilities for RSS-enabled NICs. However, it still cannot steer packets of a data flow to the same core where the application process resides. Turning again to Fig 1, process P is scheduled to run on Core 3. Its traffic might be hashed to an entry that directs to other cores. The OS does not know which specific entry in the indirection table a traffic flow will be mapped to.

With existing RSS capability, there are many cases in OSes in which a network application resides on cores other than those to which its corresponding network interrupts are directed: (1) A single-threaded application might handle multiple concurrent TCP connections. Assuming such an
application handles \( n \) concurrent TCP connections and runs on an \( m \)-core system, an RSS-enabled NIC will evenly (statistically) distribute the \( n \) connections across the \( m \) cores. Since the application can only run on a single core at any moment, only \( n/m \) connections' network interrupts are directed to the same core where the application runs. (2) Soft partitioning technologies like CPUSET [15] are applied in the context of networking environments. Since the OS (or system administrator) has no way of knowing to which specific core they will be mapped, network applications might be soft-partitioned on cores other than those to which their network interrupts are directed. (3) The general purpose OSes scheduler prioritizes load balancing or power saving over process-to-interrupt affinity [16][17]. For OSes like Linux, when the multicore peak performance mode is enabled, the scheduler tries to use all cores in parallel to the greatest extent possible, distributing the load equally among them. When the multicore power saving mode is enabled, the scheduler is biased to restrict the workload to a single physical processor. As a result, a network application might be scheduled on cores other than those to which its network interrupts are directed.

For clarity, we illustrate the above cases in Fig. 2. The system contains two physical processors, each with two cores. P1 – P5 are processes that run within the system. P1 is a network process that includes traffic flows. An RSS-enabled NIC steers the traffic flows to different cores, as shown in the figure (red arrows). In all of these cases, P1 resides on cores other than those to which its corresponding network interrupts are directed.

Fig. 2 Network Irqs and Apps. on Different Cores

On OSes like Windows, when a core responds to the network interrupt, the corresponding interrupt handler is called, within which a deferred procedure call (DPC) is scheduled. On the core, DPC processes received packets up through the network stack from the corresponding ring buffer one by one [18]. Therefore, on Windows, tying a traffic flow to a single core does ensure interrupt affinity and flow affinity. However, if network interrupts are not directed to cores on which the corresponding applications reside, network data affinity cannot be achieved, resulting in degraded cache efficiency [10]. This reality might cause serious performance degradation for NUMA systems.

On some OSes, like Linux, tying a traffic flow to a single core does not necessarily ensure flow affinity or network data affinity due to Linux TCP’s unique prequeue-backlog queue design. In the following sections, we discuss in detail why the combination of RSS and Flow Pinning cannot ensure flow affinity and network data affinity in Linux.

2.3 Linux Network Processing in Multicore Systems

As a modern parallel network stack, Linux exploits packet-based parallelism, which allows multiple threads to simultaneously process different packets from the same or different connections. Two types of threads may perform network processing in Linux: application threads in process context and interrupt threads in interrupt context. When an application makes socket-related system calls, that application’s process context may be borrowed to carry out network processing. When a NIC interrupts a core, the associated handler services the NIC and schedules the softirq, softnet. Afterwards, the softnet handler processes received packets up through the network stack in interrupt context. TCP is a connection-oriented protocol, and it has a large and frequently accessed state that must be shared and protected. In the case of the Linux TCP, the data structure socket maintains a connection’s various TCP states, and there is a per-socket lock to protect it from unsynchronized access. The lock consists of a spinlock and a binary semaphore. The binary semaphore construction is based on the spinlock. In Linux, since an interrupt thread cannot sleep, when it accesses a socket, the socket is protected with the spinlock. When an application thread accesses a socket, the socket is locked with the binary semaphore and is considered “owned-by-user.” The binary semaphore synchronizes multiple application threads among themselves. It is also used as a flag to notify interrupt threads that a socket is “owned-by-user” to coordinate synchronized access to the socket between interrupt and application threads.

Our previous research [19][20] studied the details of the Linux packet receiving process. Here, we simply summarize Linux TCP processing of the data receive path in interrupt and process contexts, respectively.

a) TCP Processing in Interrupt Context

(1) When the NIC interrupts a core, the network interrupt’s associated handler services the NIC and schedules the softirq, softnet.

(2) The softnet handler moves a packet from the ring buffer and processes the packet up through the network stack. If there is no packet available in the ring buffer, the softnet handler exits.

(3) A TCP packet (segment) is delivered up to the TCP layer. The network stack first tries to identify the socket to which the packet belongs, and then seeks to lock (spinlock) the socket.

(4) The network stack checks if the socket is “owned-by-user” or if an application thread is sleeping and awaiting data:

- If yes, the packet will be enqueued into the socket’s backlog queue or prequeue. TCP processing will be
where the application is scheduled

TCP processing is performed in interrupt context, it is performed on the cores to which the network interrupts are directed. Take, for example, Fig. 3, in which network interrupts are directed to core 0 and the associated network application is scheduled to run on core 1. In interrupt context, TCP is processed on core 0; in process context, this occurs on core 1. Since TCP processing performed in process or interrupt contexts depends on volatile runtime conditions, it may alternate between these two cores. Therefore, although the combination of RSS and Flow Pinning can tie a traffic flow to a single core, when a network application resides on some other core, TCP processing might alternate between different cores. We would achieve neither flow affinity nor network data affinity.

2.4 Negative Impacts

If an application runs on cores other than those where its corresponding RSS network interrupts are directed, various negative impacts result. On both Windows and Linux systems, network data affinity cannot be achieved. Furthermore, on OSes like Linux, TCP processing might alternate between different cores even if the interrupts for the flow are pinned to a specific core. As a result, it will lead to poor cache efficiency and cause significant core-to-core synchronization overheads. Also, it renders the DCA technology ineffective. In multiple core systems, core-to-core synchronizations involve costly snoops and MESI operations [21], resulting in extra system bus traffic. This is especially expensive when the contending cores exist within different physical processors, which usually involves synchronous read/write operations to a certain memory location.

In addition, for Linux, interrupt and application threads contend for shared resources, such as locks, when they concurrently process packets from the same flow. The socket’s spinlock, for example, would be in severe contention. When a lock is in contention, contending threads simply wait in a loop (“spin”), repeatedly checking until the lock becomes available. While waiting, no useful work is executed. Contention for other shared resources, such as memory and system bus, also occurs frequently. Since this intra-flow contention may occur on a per-packet basis, the total contention overhead could be severe in high network I/O environments.

To demonstrate the negative impacts, we ran data transmission experiments over an isolated sub-network. The sender and receiver’s detailed features are as:

**Sender:** Dell R-805. CPU: two Quad Core AMD Opteron 2346HE, 1.8GHz, HT1. NIC: Broadcom NetXtreme II 5708, 1Gbps, DCA not supported. OS: Linux 2.6.28.

**Receiver:** SuperMicro Server. CPU: two Intel Xeon CPUs, 2.66 GHz, Family 6, Model 15. NIC: Intel PRO/1000,
1Gbp, DCA not supported. OS: Linux 2.6.28. The receiver’s CPU architecture is as shown in Fig. 4.

In the experiments, we used iperf [22] to send data in one direction. The sender transmitted one TCP stream to the receiver for 100 seconds. In the receiver, network interrupts were all directed to core 0. However, iperf was pinned to different cores: (1) iperf was pinned to core 0 (network interrupts and applications were pinned to the same core). (2) iperf was pinned to core 1 (network interrupts and applications were pinned to different cores, but within the same processor). (3) iperf was pinned to core 2 (network interrupts and applications were pinned to different processors). The throughput rates in these experiments all saturated the 1Gbps link (around 940 Mbps). The experiments were designed to feature the same throughput rates for the sake of better comparisons.

We ran oprofile [23] to profile system performance in the case of the receiver. The metrics of interest were: INST RETIRED, the number of instructions retired; BUS.TRAN.ANY, the total number of completed bus transactions; and BUS.HITM.DRV, the number of HITM (hit modified cache line) signals asserted [24]. For these metrics, the number of events between samples was 10000. We also enabled the Linux Lockstat [15] to collect lock statistics. On this basis we calculated the total time spent waiting to acquire various kernel locks, and we called this WAITTIME-TOTAL. Consistent results were obtained across repeated runs. The results are as listed in Fig. 5, with a 95% confidence interval.

![Fig. 5. Experiment Results](image)

The throughput rates in these experiments all saturated the 1Gbps link. However, Fig. 5 clearly shows that the metrics of iperf @ Core 1 and Core 2 are much higher than those of iperf @ Core 0. This clearly verifies that when a network application is scheduled on cores other than those to which the corresponding network interrupts are directed, severely degraded system efficiency will result.

INST RETIRED measures the load on the receiver. The results clearly demonstrate that contention for shared resources between interrupt and application threads led to an extra load. The extra load is mainly related to time spent waiting for locks. The experimental WAITTIME-TOTAL data verify this point. It is surprising that the BUS_TRANS_ANY of iperf @ Core 2 is almost twice that of iperf @ Core 0. The BUS_HITM_DRV of iperf @ Core 0 is far less that that of iperf @ Core 1 and Core 2. Since the throughput rates in these experiments all saturated the 1Gbps link, the extra BUS_TRANS_ANY and BUS_HITM_DRV transactions of iperf @ Core 1 and Core 2 were caused by cache trashing and lock contention, as analyzed above.

2.5 Why does Flow Director cause packet reordering?

In parallel to our research, Intel has introduced the Ethernet Flow Director technology to remedy the RSS limitation. Flow Director is a NIC technology. As shown in Fig. 6, it supports multiple receive queues in the NIC, up to the number of cores in the system. Each receive queue has a dedicated interrupt and is tied to a specific core; each core in the system is assigned a specific receive queue. Flow Director maintains a “Traffic Flow → Core” table with a single entry per flow. Each entry tracks the receive queue (core) to which a flow should be assigned. Entries within the “Traffic Flow → Core” table are updated by outgoing packets. To support Flow Director, OS must be multiple TX queue capable [14]. Each core in the system is assigned a specific transmit queue. Outgoing traffic generated on a specific core is transmitted via its corresponding transmit queue. For an outgoing transport-layer packet, the OS records the transmit queue ID (processing core ID) and use it to update the corresponding entry in the table. Flow Director makes use of the 5-tuple {src_addr, dst_addr, protocol, src_port, dst_port} in the receive direction to specify a flow. Therefore, for an outgoing packet with the header {src_addr: x, dst_addr: y, protocol: z, src_port: p, dst_port: q}, its corresponding flow entry in the table is identified as {src_addr: y, dst_addr: x, protocol: z, src_port: q, dst_port: p}. Packet receiving process with Flow Director is similar to that of with RSS, except that incoming packets look up the “Traffic Flow → Core” table to identify the core and hence, the associated receive queue.

![Fig. 6 Flow Director Mechanism](image)
Flow Director not only provides the benefits of parallel receive processing in multiprocessing environments, it also can automatically steer packets of a data flow to the same core on which its application resides. However, our analysis shows that Flow Director cannot guarantee in-order packet delivery in multiprocessing environments. In the following section, we use a simplified model to analyze why this is the case.

As shown in Fig. 7, at time $T - \varepsilon$, Flow 1’s flow entry maps to Core 0 in the “Traffic Flow → Core” table. At this instant, packet $S$ of Flow 1 arrives; based on the “Traffic Flow → Core” table, it is assigned to Core 0. At time $T$, due to process migration, Flow 1’s flow entry is updated and maps to Core 1. At $T + \varepsilon$, Packet $S + 1$ of Flow 1 arrives and is assigned to the new core, namely Core 1. As described above, after assigning received packets to the corresponding receive queues, NIC copies them into system memory via DMA, and fires network interrupts, if necessary. When a core responds to a network interrupt, it processes received packets up through the network stack from the corresponding ring buffer one by one. In our case, Core 0 processes packet $S$ up through the network stack from Ring Buffer 0, and Core 1 services packet $S + 1$ from Ring Buffer 1. Let $T_{\text{service}}(S)$ and $T_{\text{service}}(S + 1)$ be the times at which the network stack starts to service packets S and S+1, respectively. If $T_{\text{service}}(S) > T_{\text{service}}(S + 1)$, the network stack would receive packet S+1 earlier than packet S, resulting in packet reordering. Let D be the ring buffer size and let the network stack’s packet service rate be $R_{\text{service}}$ (packets per second). Assume there are $n$ packets ahead of S in Ring Buffer 0 and $m$ packets ahead of S+1 in Ring Buffer 1. Then:

$$T_{\text{service}}(S) = T + \varepsilon + n / R_{\text{service}} \quad (1)$$

$$T_{\text{service}}(S + 1) = T + \varepsilon + m / R_{\text{service}} \quad (2)$$

If $\varepsilon$ is small and $n > m$, the condition of $T_{\text{service}}(S) > T_{\text{service}}(S + 1)$ would easily hold and lead to packet reordering. Since the ring buffer size is $D$, the worst case is $n = D - 1$ and $m = 0$:

$$T_{\text{service}}(S) = T + \varepsilon + (D - 1) / R_{\text{service}} \quad (3)$$

$$T_{\text{service}}(S + 1) = T + \varepsilon \quad (4)$$

The ring buffer size D is a design parameter for the NIC and driver. For example, the Myricom 10Gb NIC is 512, and Intel’s 1Gb NIC is 256.

In a multicore system, a general-purpose OS scheduler tries to use all core resources in parallel as much as possible, distributing and adjusting the load among the cores. Process migration across cores occurs frequently. The conditions for Flow Director to cause packet reordering can be easily satisfied. As a result Flow Director can easily cause packet reordering.

To validate our analysis, we ran data transmission experiments over an isolated network. A sender was directly connected to a receiver via a physical 10Gbps link. The sender and receiver are the same computer systems as specified in Section 2.4, except that:

**Sender**: NIC: Myricom 10Gbps Ethernet NIC.

**Receptor**: NIC: Intel X520 Server Adapter with Flow Director enabled (configured with suggested default parameters [14]: FdirMode=1, AtrSampleRate=20), 10Gbps. OS: Linux 2.6.34, Multiple TX Queue Capable.

The experiments relied on the following: (1) Iperf is a multi-threaded network application. With multiple parallel TCP data streams, a dedicated child thread is spawned and assigned to handle each stream in the system. (2) When Iperf is pinned to a specific core, its child threads are also pinned to that core. In the first experiment, Iperf was used to send $n$ parallel TCP streams from sender to receiver for 100 seconds. We ran “iperf -s” in the receiver. Linux was configured to run in multiprocess peak performance mode [16][17]. As a consequence, the scheduler tried to use all core resources in parallel as much as possible, distributing the load equally among the cores. Iperf threads would migrate across cores. The receiver was instrumented to record out-of-order packets, and we calculated relevant packet reordering ratios. The experiment results, with a 95% confidence interval, are shown in Table 1.

The degree of packet reordering is significant.

At $n = 200$, packet reordering ratio reached as high as 0.897%. The experiment results validated our analysis. When the scheduler tried to distribute the load equally among the cores, frequent process migration will result. As our analysis suggested, the Flow Director mechanism would cause packet reordering when process migration occurs.

In the second experiment, we then ran “taskset 0x01” Iperf -s” in the receiver to pin Iperf to core 0 and repeated the above experiments. No packet reordering was discovered. This is because when Iperf is pinned to a specific core, its child threads are also pinned to that core. There will be no process migration. The conditions for Flow Director to cause packet reordering are not satisfied.

### 3. A Transport Friendly NIC (A-TFN)

#### 3.1 A-TFN Design Principles & Alternatives

Previous analyses and experiments clearly show that, existing RSS-enabled NICs cannot automatically steer incoming network data to the core on which its application process resides, and Flow Director cannot ensure in-order packet delivery. In this paper, we propose a NIC mechanism to remedy the RSS and Flow Director limitations. It steers incoming network data to the same core on which its application resides and ensures in-order packet delivery. Our data steering mechanism is mainly targeted at TCP, but can be extended to UDP and SCTP. We term a NIC with such a data steering mechanism A Transport-Friendly NIC, or A-TFN.
We base our A-TFN design on two observations. First, a TCP connection’s traffic is bidirectional. For a unidirectional data flow, ACKs on the reverse path result in bidirectional traffic. Second, when an application makes socket-related system calls, that application’s process context would be borrowed to carry out network processing in process context. This is true and common for all general purpose OSES although their network stacks are implemented differently. In the data transmit path, network processing starts in the process context when an application makes socket-related system calls to send data. If TCP gives permission to send, network processing in process context can reach down to the bottom of the protocol stack. In the data receive path, when an application thread makes socket-related receive system calls to move data from the socket into the user space, it needs to generate ACKs to advertise new receive window sizes. These ACKs are generated in process context.

A-TFN’s basic idea is simple: it maintains the relationship “Traffic Flows → Cores (Applications) in the NIC, with OSES correspondingly enhanced to support such capability. For transport layer traffic, A-TFN maintains a Flow-to-Core table in the NIC, with one entry per flow. Each entry tracks which receive queue (core) a flow should be assigned to. With each outgoing transport-layer packet (including ACK packet), the OS records a processor core ID and uses it to update the entry in the Flow-to-Core table. As soon as any network processing is performed in a process context, A-TFN learns of the core on which an application process resides and can steer future incoming traffic to the right core. This is a key point that A-TFN is different from Flow Director.

Clearly, the design of such a mechanism involves a trade-off between the amount of work done in the NIC and in the OS. There are two design options. Option 1 is to minimize changes in the OS and focuses instead on identifying the minimal set of mechanisms to add to the NIC. Clearly, this design adds complexity and cost to the NIC. On the other end of the design space, it could be let the OS update the flow-to-core table directly without changing anything in the NIC hardware (option 2). Conceptually, this approach could be fairly straightforward to implement. However, it might add significant extra communication overheads between the OS and the NIC, especially when the Flow-to-Core table gets large. Due to space limitation, this paper is mainly focused on the first design option. In our future work, we will explore the second design option. Besides, option 1 design has other goals: (1) A-TFN must be simple and efficient. NIC controllers usually utilize a less powerful CPU with a simplified instruction set and insufficient memory to hold complex firmware. (2) A-TFN must preserve in-order packet delivery. (3) The communication overheads between the OS and A-TFN must be minimal.

### 3.2 A-TFN Details

Fig. 8 illustrates the A-TFN details. A-TFN extends the current RSS technologies. It supports multiple receive queues in the NIC, up to the number of cores in the system. With MSI and Flow-Pinning support, each receive queue has a dedicated interrupt and is tied to a specific core. Each core in the system is assigned a specific receive queue. A-TFN handles non-transport layer traffic in the same way as does RSS. That is, based on a hash of the incoming packet’s headers, the NIC assigns it to the same queue as other packets from the same data flow, and distributes different flows across queues. For transport layer traffic, A-TFN maintains a Flow-to-Core table with a single entry per flow. Each entry tracks the receive queue (core) to which a flow should be assigned. The entries within the Flow-to-Core table are updated by outgoing packets. For unidirectional TCP data flows, outgoing ACKs update the Flow-to-Core table. For an outgoing transport-layer packet, the OS records a processing core ID in the transmit descriptor and passes it to the NIC. Since each packet contains a complete identification of the flow it belongs to, the specific Flow → Core relationship could be effectively extracted from the outgoing packet and its accompanying transmit descriptor. As soon as any network processing is performed in process context, A-TFN learns of which core an application resides.

![Fig. 8 A-TFN Mechanisms](image)

### 3.3 Flow-to-Core Table and its Operations

The Flow-to-Core table appears in Fig. 9. Flow entries are managed in a hash table, with a linked list to resolve collisions. Each entry consists of:

- **Traffic Flow.** A-TFN makes use of the 5-tuple \{src_addr, dst_addr, protocol, src_port, dst_port\} in the receive direction to specify a flow. Therefore, for an outgoing packet with the header \{(src_addr: x), (dst_addr: y), (protocol: z), (src_port: p), (dst_port: q)\}, its corresponding flow entry in the table is identified as \{(src_addr: y), (dst_addr: x), (protocol: z), (src_port: q), (dst_port: p)\}.

- **Core ID.** The core to which the flow should be steered.

- **Transition State.** A flag to indicate if the flow is in a transition state. The goal is to ensure in-order packet delivery.
Packets in Transition. A simple packet list to accommodate temporary packets when the flow is in a transition state. The goal is to ensure in-order packet delivery.

In addition, to avoid non-deterministic packet processing time, a collision-resolving linked list is limited to a maximum size of MaxListSize. Flows are not evicted in case of collision. When a specific hash’s collision-resolving list reaches MaxListSize, later flows with that hash will not be entered into the table.

a) Flow Entry Generation and Deletion

A-TFN monitors each incoming and outgoing packet to maintain the Flow-to-Core Table. An entry is generated in the Flow-to-Core table as soon as A-TFN detects a successful three-way handshake. However, to reduce NIC complexity, A-TFN need not run a full TCP state machine in the NIC. A flow entry is deleted after a configurable period of time, $T_{deln}$, has elapsed without traffic. In this way, A-TFN need not handle all exceptions such as missing FIN packets and various timeouts.

To prevent memory exhaustion or malicious attacks, A-TFN sets an upper bound on the number of entries in the Flow-to-Core Table. When the Flow-to-Core table starts to become full, TCP flows can be aged out more aggressively by using a smaller $T_{deln}$. For traffic flows that are not in the Flow-to-Core table, packets are delivered based on a hash of the incoming packets’ headers.

b) Flow Entry Updating

The entries of the Flow-to-Core table are updated by outgoing packets. For each outgoing transport-layer packet, the OS records a processing core ID in the transmit descriptor and passes it to the NIC. A naive way to update the corresponding flow entry is with the passed core ID, omitting any other measures. As soon as any network processing is performed in process context, A-TFN will learn of the process migration and can steer future incoming traffic to the right core. However, this simple flow entry updating mechanism cannot guarantee in-order packet delivery. In Section 2.5, we use a simplified model to analyze why Flow Director cannot guarantee in-order packet delivery. The model and analysis can be also applied here. As we have analyzed, if $\epsilon$ is small and $n > m$, the condition of $T_{service}(S) > T_{service}(S + 1)$ would easily hold and lead to packet reordering. Since the ring buffer size is $D$, the worst case is $n = D - 1$ and $m = 0$. It would have $T_{service}(S) = T - \epsilon + (D - 1)/R_{service}$ and $T_{service}(S + 1) = T + \epsilon$. TCP performance suffers in the event of severe packet reordering [25].

However, if the delivery of packet $S + 1$ to Core 1 can be delayed for at least $(D - 1)/R_{service}$, then $T_{service}(S + 1) = T - \epsilon + (D - 1)/R_{service}$. As a result, $T_{service}(S + 1) > T_{service}(S)$ and in-order packet delivery can be guaranteed. Therefore, A-TFN adopts the following flow entry updating mechanism: for each outgoing transport-layer packet, the OS records a processing core ID in the transmit descriptor and passes it to the NIC to update the corresponding flow entry. For a TCP flow entry, if the new core id is different from the old one, the flow enters the “transition” state. Correspondingly, its “Transition State” is set to “Yes” and a timer is started for this entry. The timer’s expiration value is set to $T_{timer} = (D - 1)/R_{service}$. Incoming packets of a flow in the transition state are added to the tail of “Packets in Transition” instead of being immediately delivered. When the timer expires, the flow leaves the transition state. The “Transition State” is set back to “No” and all of the packets in “Packets in Transition,” if they exist, are assigned to the new core. For a flow in the “non-transition” state, its packets are directly steered to the corresponding core. With current computing power, $(D - 1)/R_{service}$ is usually at the sub-millisecond level, at best. For A-TFN, $T_{timer}$ is a design parameter and is configurable.

Flow Director does not have an effective mechanism to ensure in-order packet delivery.

3.4 Required OS Support

A-TFN design requires only two small OS changes in order to be properly supported. These can be easily implemented. (1) For an outgoing transport-layer packet, the OS needs to record a processing core ID in the transmit descriptor passed to the NIC. (2) The transmit descriptor needs to be updated with a new element to store this core ID. A single-byte element can support up to 256 cores, which is sufficient for most of today’s systems. In addition, the size of a transmit descriptor is usually small, typically less than a cache line. Transmit descriptors are usually copied to the NIC by DMA using whole cache line memory transactions. Adding a byte to the transmit descriptor introduces almost no extra communication overhead between the OS and NIC.

4. Analysis and Experiments

The A-TFN mechanism is simple. It guarantees in-order packet delivery and requires the most minimal OS support. In addition, the communication overheads between the OS and A-TFN are reduced to a minimum. Compared to the extensively pursued TCP Offloading Engine (TOE) technology, which seeks to offload processing of the engine TCP/IP stack to the NIC, A-TFN is much less complex. A-TFN does not require a complicated TCP engine within the NIC. There is also no need to synchronize TCP flow states between the OS and A-TFN. Finally, there is no need to enforce flow access control in the NIC. Therefore, A-TFN can be effectively implemented with current hardware and software technologies. In the following sections, we use a combination of analytical and experimental techniques to evaluate the effectiveness of A-TFN mechanisms.

4.1 Analytical Evaluation

a) Delay

To ensure in-order packet delivery, incoming packets of a flow in the transition state are added to the tail of “Packets in Transition”. These packets are delivered later, when the flow exits the transition state. Obviously, the A-TFN mechanism can add delay to certain packets. Clearly, the
maximum delay a held packet can experience is $T_{inner}$. Previous analysis has shown that in-order packet delivery is guaranteed when $T_{inner}$ is set to $(D - 1)/R_{server}$. However, in the real world, incoming packets rarely fill a ring buffer. If $T_{inner}$ were configured to be smaller, this would still ensure in-order packet delivery in most cases. In [25], we record the duration for which the OS processes the ring buffer. Our experiments have clearly shown that the duration is generally shorter than 20 microseconds. In most cases the extra delay is so small that it can be ignored.

b) Flow Affinity and Network Data Affinity

The intent of A-TFN is to automatically steer incoming network data to the same core on which its application process resides. As soon as any network processing is performed in a process context, A-TFN learns of the core on which an application process resides and can steer future incoming traffic to the right core. As a result, the desired flow affinity and network data affinity are guaranteed.

c) Hardware design considerations

A-TFN’s memory is mainly used to maintain the Flow-to-Core table, holding flow entries and accommodating packets for flows in the transition state. To hold a single flow entry, 20 bytes is quite sufficient. Therefore, a 10,000-entry Flow-to-Core table requires only 0.2 MB of memory. (These figures apply to IPv4; IPv6 support would add 24 bytes to the size of each entry, or less if the flow label could be relied upon.) In addition, to accommodate packets for flows in transition, if $T_{inner}$ is set to 0.2 millisecond, even for a 10Gbps NIC, the memory required is $0.2 \text{ millisecond} \times 10Gbps = 0.25 \text{ MB}$, at maximum. In the worst case, an extra 0.5 MB of fast SRAM is enough to support the Flow-to-Core Table. A Cypress 4Mb (10ns) SRAM now costs around $7, with ICC=90 mA@10ns and ISB2=10mA. Table 2 lists the cost, memory size and power consumption of three popular 10G Ethernet NICs in the market. Clearly, A-TFN’s requirement of an extra 0.5 MB fast SRAM in the NIC won’t add much extra cost (< 1%) and power consumption (<5% for Intel and Chelsio; <10% for Myricom) to current 10Gbps NICs.

A linked list in HW is expensive to build given all the extra handling. However, there will be a tradeoff in hardware complexity and A-TFN effectiveness. We discuss this later.

<table>
<thead>
<tr>
<th>Vendor</th>
<th>Cost</th>
<th>Memory</th>
<th>Power</th>
</tr>
</thead>
<tbody>
<tr>
<td>Intel</td>
<td>$1500</td>
<td>N/A</td>
<td>10.4W</td>
</tr>
<tr>
<td>Chelsio</td>
<td>&gt; $750</td>
<td>256MB</td>
<td>16W</td>
</tr>
<tr>
<td>Myricom</td>
<td>$ 850</td>
<td>2MB SRAM</td>
<td>4.1W</td>
</tr>
</tbody>
</table>

Table 2 10G PCI-Express Ethernet NICs, Single Network Port, 10GBase-SR, Optics Fiber Transceiver

4.2 Experimental Evaluation

We prototyped an A-TFN system as shown in Fig. 10A. A sender connects to a receiver via two physical back-to-back 10Gbps links. The sender and receiver are the same computer systems as specified in Section 2.4. The 10Gbps links are driven by Myricom 10Gbps Ethernet NICs. In both

the sender and the receiver, the two Myricom 10Gbps NICs are aggregated into a single logical bonded interface with the Linux bonding driver. In the sender, the bonding driver is modified with A-TFN mechanisms and each 10Gbps link is deemed an A-TFN receive queue. In the receiver, each slave NIC (receive queue) is pinned to a specific core. In addition, the receiver’s OS is modified to support the A-TFN mechanisms. For an outgoing transport-layer packet, the OS records a processing core ID in the “transmit descriptor” and passes it to “A-TFN.” Here, we make use of four reserved bits in the TCP header as the “transmit descriptor” to communicate the core ID. When the sender receives a “transmit descriptor,” it extracts the passed Core ID and updates the corresponding flow entry in the Flow-to-Core table. Unless otherwise specified, $T_{inner}$ is set to 0.1 millisecond. The Flow-to-Core table is upped limited to 10,000 entries.

Similarly, we implemented a two-receive queue RSS NIC, as shown in Fig. 10B. In both the sender and the receiver, the two Myricom 10Gbps NICs are aggregated into a single logical bonded interface with the bonding driver. In the sender, the bonding driver is modified with RSS mechanisms, and each 10Gbps link is treated as an RSS receive queue. Unless otherwise specified, the hashing is based on the combination of $\{src\_addr, dst\_addr, src\_port, dst\_port\}$ for each incoming packet. In the receiver, each slave NIC (receive queue) is pinned to a specific core.

We ran data transmission experiments with iperf using the test system shown in Fig. 10. In our experiments, iperf sends with $n$ parallel TCP streams for 100 seconds, to ports 5001 and 6001, respectively. Therefore, totally $2n$ parallel TCP streams are transmitting in each experiment. The number $n$ was varied across experiments. The experiment scripts for the sender appear in Listing 1. In the receiver, the receive queues and iperf are pinned to different cores to simulate a two-core system. The experimental configurations are listed in Table 3. We did not include Flow Director in the experiments. The
experiments in Section 2.5 have already showed that Flow Director could cause packet reordering in multiprocessing environments.

In our emulated system, we measure the Flow-to-Core Table’s search time. The search time to access the first item in a collision-resolving linked list takes around 260 ns, which includes the hashing and locking overheads. For each next item in the list, it takes approximately an extra 150 ns. Therefore, the longest search in our system takes $260 + 150 \times (\text{MaxListSize} - 1)$ ns. For a 10Gb/s NIC, the time budget to process a 1500-byte packet is around 1200 ns. To evaluate MaxListSize’s effect on A-TFN’s performance, we set MaxListSize to 1 and 6, respectively. Correspondingly, A-TFN is termed as A-TFN-1 and A-TFN-6.

a) Performance Experiments

Experiments 1 and 2 simulated the network conditions that a single-threaded application must handle multiple concurrent TCP connections. In both experiments, TCP streams of a specific port (5001 or 6001) were pinned to a particular core. Given the same experimental conditions, we compared the results with A-TFN to those with RSS. The metrics of interest were: (1) Throughput; (2) WAITTIME-TOTAL; and (3) BUS_HITM_DRV. (The number of events between samples was 10000.) Consistent results were obtained across repeated runs. All results presented are shown with a 95% confidence interval.

As analyzed in previous sections, when a single network application handles multiple concurrent TCP connections, the hashing function of the RSS-enabled NIC will evenly and statistically distribute the connections across the cores. Since the application can only run on a single core at any given moment, some connections get steered to cores other than the one on which the application runs. As a result, TCP processing will alternate between different cores. This fact may even lead to contention for shared resources between interrupt and application threads when they concurrently process packets of the same flows. Under such circumstances, overall system efficiency could be severely degraded. The experimental results in Tables 4, 5, and Fig. 11 confirm these points. To save space, we put experiment 1’s results in Table 4 and 5. In experiment 2, Core 0 and 2 reside in two separate physical processors. The results can better demonstrate the RSS limitation. We present them in Fig. 11.

b) Reordering Experiments

Experiments 3 and 4 simulated the network conditions that a single-threaded application must handle multiple concurrent TCP connections. In both experiments, TCP streams of a specific port (5001 or 6001) were pinned to a particular core. Given the same experimental conditions, we compared the results with A-TFN to those with RSS. The metrics of interest were: (1) Throughput; (2) WAITTIME-TOTAL; and (3) BUS_HITM_DRV. (The number of events between samples was 10000.) Consistent results were obtained across repeated runs. All results presented are shown with a 95% confidence interval.

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<table>
<thead>
<tr>
<th>Experiments</th>
<th>Receive Queues Config.</th>
<th>Iperf Config.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Exp. 1</td>
<td>Receive queue 0 @ Core 0</td>
<td>“iperf –s –p 5001” @ Core {0}</td>
</tr>
<tr>
<td></td>
<td>Receive queue 1 @ Core 1</td>
<td>“iperf –s –p 6001” @ Core {1}</td>
</tr>
<tr>
<td>Exp. 2</td>
<td>Receive queue 0 @ Core 0</td>
<td>“iperf –s –p 5001” @ Core {0}</td>
</tr>
<tr>
<td></td>
<td>Receive queue 1 @ Core 2</td>
<td>“iperf –s –p 6001” @ Core {2}</td>
</tr>
<tr>
<td>Exp. 3</td>
<td>Receive queue 0 @ Core 0</td>
<td>“iperf –s –p 5001” @ Core {0, 1}</td>
</tr>
<tr>
<td></td>
<td>Receive queue 1 @ Core 1</td>
<td>“iperf –s –p 6001” @ Core {0, 1}</td>
</tr>
<tr>
<td>Exp. 4</td>
<td>Receive queue 0 @ Core 0</td>
<td>“iperf –s –p 5001” @ Core {0, 2}</td>
</tr>
<tr>
<td></td>
<td>Receive queue 1 @ Core 2</td>
<td>“iperf –s –p 6001” @ Core {0, 2}</td>
</tr>
</tbody>
</table>

Table 3 Experiment Configurations in the Receiver

<table>
<thead>
<tr>
<th>$2n$</th>
<th>WAITTIME-TOTAL (Nanoseconds)</th>
<th>BUS_HITM_DRV (X10000)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RSS A-TFN-1 A-TFN-6 RSS A-TFN-1 A-TFN-6</td>
<td></td>
</tr>
<tr>
<td>40</td>
<td>703819±1199 87371±1818 2913±137 12710±16 7081±31 6716±191</td>
<td></td>
</tr>
<tr>
<td>200</td>
<td>663459±27854 257794±10544 6772±330 11933±18 7691±38 5937±181</td>
<td></td>
</tr>
<tr>
<td>1000</td>
<td>738267±242107 472195±240886 68778±12502 7001±513 4620±598 3150±1087</td>
<td></td>
</tr>
<tr>
<td>2000</td>
<td>1673063±406510 974218±219541 511629±191570 5452±799 5432±106 3713±812</td>
<td></td>
</tr>
</tbody>
</table>

Table 4 Experiment 1 Results (WAITTIME-TOTAL & BUS HITM DRV)

<table>
<thead>
<tr>
<th>$2n$</th>
<th>Throughput (Gbps)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RSS A-TFN-1 A-TFN-6</td>
</tr>
<tr>
<td>40</td>
<td>14.65±0.04 14.77±0.01 14.82±0.08</td>
</tr>
<tr>
<td>200</td>
<td>13.39±0.04 13.51±0.02 13.62±0.04</td>
</tr>
<tr>
<td>1000</td>
<td>5.93±0.64 6.05±0.87 6.15±0.85</td>
</tr>
<tr>
<td>2000</td>
<td>5.2±0.54 5.44±0.93 6.06±0.79</td>
</tr>
</tbody>
</table>

Table 5 Experiment 1 Results (Throughput)
experiment 1, core 0 and 1 reside in the same physical processor, while in experiment 2, core 0 and 2 reside in different physical processors. Core-to-core synchronization is more expensive when the contending cores exist in different physical processors. Therefore, A-TFN is more effective in NUMA systems.

For the Flow-to-Core table, when a specific hash’s collision-resolving lined list reaches MaxListSize, subsequent flows for that hash will not be entered into the table. Their packets are delivered in the same way as does RSS. It can be seen that with $2n=40$, A-TFN-1’s results (especially for throughputs) are very close to those of A-TFN-6’s. With $2n=2000$, A-TFN-1 behaves closer as does RSS. We record the percentage of flows that are entered into the Flow-to-Core table when $n$ is varied (Table 6). It clearly shows that as $n$ increases, the percentage of flows that are entered into the table decreases, with the effects on A-TFN-1 being much more than on A-TFN-6. With $2n=2000$, A-TFN-1 has only a 12.7% of flows entered into the Flow-to-Core table. The reason the ratio is so low is because all the flows share a single pair of IP addresses, they are not hashed efficiently across the table. As a result, more traffic would be delivered in the same way as RSS does. From the hardware implementation’s perspective, A-TFN-1’s Flow-to-Core table is much easier to implement. But its performance is not satisfactory as the number of TCP streams increase. Thus, there will be a tradeoff in hardware complexity and A-TFN effectiveness. It is anticipated that with $n$ further increased, A-TFN-6 would have more traffic delivered in the way as RSS does; its effectiveness would start to decrease as well. Normally, a high-end web server would handle a few thousand concurrent TCP streams. For our two-core A-TFN emulated system, 2000 streams is quite a high number. Since the trend is already very clear, we don’t further increase $n$.

<table>
<thead>
<tr>
<th>$2n$</th>
<th>A-TFN-6</th>
<th>A-TFN-1</th>
</tr>
</thead>
<tbody>
<tr>
<td>40</td>
<td>100% ± 0</td>
<td>88% ± 1.6%</td>
</tr>
<tr>
<td>200</td>
<td>100% ± 0</td>
<td>71% ± 2.9%</td>
</tr>
<tr>
<td>1000</td>
<td>95.7% ± 1.1%</td>
<td>24.5% ± 0.1%</td>
</tr>
<tr>
<td>2000</td>
<td>71.7% ± 0.2%</td>
<td>12.7% ± 0%</td>
</tr>
</tbody>
</table>

Table 6 Flows @ Flow-to-Core Table Percentage

With RSS technologies, the worst cases occur when soft partition technologies, like CPUSET, are applied in the networking environments. This can easily lead to the undesirable situation in which network applications are soft-partitioned on cores other than those to which their network interrupts are directed. Also, an OS scheduler prioritizes load balancing (or power saving) over process-to-interrupt affinity. In these environments, network applications may also be scheduled on cores other than those where their corresponding network interrupts are directed. We ran experiments in these environments. Conclusions similar to those above can be drawn, but due to space limitations, those results are not presented here.

b) Reordering Experiments

Different from Flow Director, A-TFN uses a special flow entry updating mechanism to guarantee in-order packet delivery. Experiments 3 and 4 were designed to evaluate whether this mechanism actually works. In both experiments, iperfs (ports 5001 and 6001) were allowed to run on both cores where the two receive queues were pinned. Linux was configured to run in multicore peak performance mode, in which the scheduler tries to distribute the load equally among the cores. As a result, iperf threads may migrate across cores. The receiver was instrumented to record any out-of-order packets, and we calculated relevant packet reordering ratios. For A-TFN-6, we set $T_{\text{timer}}$ to 0 or 100 µs. The experimental results, with a 95% confidence interval, are shown in Table 7.
When $T_{inner}$ is 0, incoming packets of a flow in the transition state are immediately delivered, instead of being added to the tail of "Packets in Transition." As discussed in Section 3.3, this could lead to packet reordering. The results in Table 7 reflect this fact. When $T_{inner}$ is 100 $\mu$s, no out-of-order packets are recorded. This shows that A-TFN can effectively guarantee in-order packet delivery.

5. Related Works

Over the years, research on affinity in network processing has been extensive. Salehi et al. [4] studied the effectiveness of affinity-based scheduling in multiprocessor network protocol processing using both packet-level and connection-level parallelization approaches. But since these approaches worked in the user space, they did not consider either system or implementation costs. In [5] and [6], A. Foong et al. experimented with affinitizing processes/threads, as well as interrupts from NICs, to specific processors in an SMP system. Experimental results suggested that processor affinity in network processing contexts can significantly improve overall performance. In [7], J. Hye-Churn et al. studied the problem of multi-core aware processor affinity for TCP/IP over multiple network interfaces, using a software-only approach. Their research topics are similar to us.

Other researchers have adopted a hard partition approach [26][27][28]. In multiprocessor environments, a subset of the processor is dedicated to network processing; the remaining processors perform only application-relevant computations. Applications interact with network processing using synchronous or asynchronous I/O interfaces. The limitation of this approach is that the OS architecture requires significant changes.

The NIC technologies, such as Intel's vmdq [29] or the PCI-SIG's SR-IOV [30], also provide data steering capabilities for the NICs. But they are I/O virtualization technologies targeting at virtual machines in the virtualized environment, not targeting at general purpose OSes in the non-virtualized environment.

The Intel Ethernet Flow Director technology [13] has been recently introduced. Flow Director maintains the relationship "Traffic Flows $\rightarrow$ Cores (Applications)" in the NIC. OSes are correspondingly enhanced to support such capability. Flow Director not only provides the benefits of parallel receive processing in multiprocessor environments, it also can automatically steer packets of a specific data flow to the same core, where they will be protocol-processed and finally consumed by the application. However, Flow Director can cause significant packet reordering in multiprocessor environments.

The Receive Packet Steering (RPS) [31] and Receive Flow Steering (RFS) [32] technologies are recently introduced. RPS spreads incoming packets out across all of the CPUs available, and RFS calculates which cores would be best suited for processing, given factors such as which applications will be using the network traffic. Both RPS and RFS are OS software technologies, instead of NIC technologies. They make use of an extra core in a multicore system to spread and steer incoming packets to other cores. RPS and RFS complement the RSS and A-TFN mechanisms. They are applied when NIC does not support RSS or A-TFN.

6. Conclusion and Discussion

Existing RSS-enabled NICs cannot automatically steer incoming network data to the core on which its application process resides. This causes various negative impacts. To remedy the RSS limitation, the Intel Ethernet Flow Director technology has been introduced. Flow Director steers packets of a specific data flow to the same core, where they will be protocol-processed and finally consumed by the application. However, Flow Director can cause significant packet reordering in multiprocessor environments. We propose an A-TFN mechanism to remedy the limitations in RSS and Flow Director. In the paper, we discuss two A-TFN design options. Option 1 is to minimize changes in the OS and focuses instead on identifying the minimal set of mechanisms to add to the NIC. On the other end of the design space, it could be let the OS update the flow-to-core table directly without changing anything in the NIC hardware (option 2). Conceptually, this approach could be fairly straightforward to implement. However, it might add significant extra communication overheads between the OS and the NIC, especially when the Flow-To-Core table gets large. Due to space limitation, this paper is mainly focused on the first design option. The new NIC is emulated in software. The experimental results show our solution is effective and practical to remedy the limitations we have identified in RSS and Flow Director. In future work, we will explore the second design option.

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